

Effect of Noise on Front Propagation in Reaction-Diffusion equations of KPP type

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Abstract

We consider reaction-diffusion equations of KPP type in one spatial dimension, perturbed by a Fisher-Wright white noise, under the assumption of uniqueness in distribution. Examples include the randomly perturbed Fisher-KPP equations

$$\partial_t u = \partial_x^2 u + u(1 - u) + \epsilon \sqrt{u(1 - u)} \dot{W}, \quad (0.1)$$

and

$$\partial_t u = \partial_x^2 u + u(1 - u) + \epsilon \sqrt{u} \dot{W}, \quad (0.2)$$

where $\dot{W} = \dot{W}(t, x)$ is a space-time white noise.

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We prove the Brunet-Derrida conjecture that the speed of traveling fronts is asymptotically

$$2 - \pi^2 |\log \epsilon^2|^{-2} \quad (0.3)$$

up to a factor of order $(\log |\log \epsilon|) |\log \epsilon|^{-3}$.

1 Randomly perturbed KPP and the Brunet-Derrida conjecture

In this article we study randomly perturbed Kolmogorov-Petrovsky-Piscunov (KPP) equations,

$$\partial_t u = \partial_x^2 u + f(u) + \epsilon \sigma(u) \dot{W} \quad t \geq 0, \quad x \in \mathbf{R}, \quad u \geq 0 \quad (1.1)$$

where $\dot{W} = \dot{W}(t, x)$ is two-parameter white noise; f is assumed to be a Lipschitz function satisfying standard KPP conditions,

$$f(0) = f(1) = 0; \quad 0 < f(u) \leq u f'(0), \quad u \in (0, 1), \quad (1.2)$$

and in addition that for $u \geq 1$,

$$f(u) \leq 2 - u. \quad (1.3)$$

We can and will rescale so that $f'(0) = 1$. We assume that $\sigma^2(u)$ is a Lipschitz function satisfying

$$\sigma^2(u) \leq u \quad (1.4)$$

and for which there exist $a^* > 0$ and $0 < u^* < 1$ such that

$$\sigma^2(u_2) - \sigma^2(u_1) \geq a^*(u_2 - u_1), \quad \text{for } 0 \leq u_1 < u_2 \leq u^*. \quad (1.5)$$

We will consider (1.1) with initial data $u(0, x) = u_0(x)$ satisfying, for some $x_0 \in \mathbf{R}$,

$$u_0(x) \geq \theta > 0, \quad x \leq x_0, \quad \text{and} \quad \int_{x_0}^{\infty} u_0(x) dx < \infty \quad (1.6)$$

and contained in some subset $\hat{\mathcal{C}}$ of the set \mathcal{C}_{exp} of non-negative continuous functions f on \mathbf{R} with $f(x) \leq C e^{|x|}$ for some $C < \infty$, for which we know

$$u_0(x) \in \hat{\mathcal{C}} \quad \Rightarrow \quad u(t, x) \in \hat{\mathcal{C}} \quad \forall t > 0, \quad P - \text{a.s.} \quad (1.7)$$

$$\text{Weak uniqueness holds in } \hat{\mathcal{C}}. \quad (1.8)$$

Key examples are

$$f(u) = u(1 - u) \quad (1.9)$$

and

$$\sigma^2(u) = u(1 - u)\mathbf{1}(u \leq 1) \quad (1.10)$$

or

$$\sigma^2(u) = u \quad (1.11)$$

with $u_0(x) \in [0, 1]$ for (1.10) and u_0 satisfying $e^{-x} \geq u_0(x)$ for (1.11). (1.9) with (1.10) appears as the limit of the long range voter model and with (1.11) as the limit of the long range contact process (see [MT95]).

Note that (1.3) is not relevant for models such as (1.10) where $0 \leq u(t, x) \leq 1$ for all time. But some condition on large u is needed in cases such as (1.11) where fluctuations can take the solution above 1.

We regard the stochastic partial differential equation (SPDE) (1.1) as shorthand for the integral equation,

$$\begin{aligned} u(t, x) = & \int G(0, y, t, x) u_0(y) dy + \int \int_0^t G(s, y, t, x) f(u(s, y)) ds dy \\ & + \int \int_0^t G(s, y, t, x) \sigma(u(s, y)) W(ds, dy), \end{aligned} \quad (1.12)$$

where $G(s, y, t, x) = G(t - s, y - x)$ is the heat kernel

$$G(t, x) = (4\pi t)^{-1/2} \exp\{-x^2/4t\}, \quad (1.13)$$

and the white noise \dot{W} is defined by specifying, for square integrable deterministic functions $\varphi(s, y)$, that $W(\varphi) := \int \int_0^\infty \varphi(s, y) W(ds, dy)$ are a Gaussian family with mean zero and covariance

$$E[W(\varphi)W(\psi)] = \int \int_0^\infty \varphi(s, y) \psi(s, y) ds dy. \quad (1.14)$$

Here, and throughout, $\int f dx$ means the integral over the entire real line \mathbf{R} . Solutions to (1.12) are called *mild solutions*. See [Wal86] for the definition of the stochastic integral in (1.12). Readers unfamiliar with SPDE can think of the following system of ordinary stochastic differential equations on $\mathbf{R}^{\frac{1}{n}\mathbf{Z}}$,

$$du_{i/n} = [n^2(u_{(i+1)/n} - 2u_{i/n} + u_{(i-1)/n}) + f(u_{i/n})]dt + n^{1/2}\epsilon\sigma(u_{i/n})dB_{i/n}, \quad (1.15)$$

where $B_{i/n}(t)$ are independent standard Brownian motions, and n is large. A corresponding evolution of functions on \mathbf{R} is produced by connecting the points $(i/n, u_{i/n})$ and $((i+1)/n, u_{(i+1)/n})$ by straight lines, and (1.1) is obtained in the weak limit as $n \rightarrow \infty$.

When $\epsilon = 0$, (1.1) with f of the form (1.9) is the standard KPP, or Fisher-KPP equation, introduced in 1937 by both Fisher [F], and Komogorov, Petrovskii, and Piscuinov [KPP]. The basic facts in this case are: There is a one-parameter family F_v of traveling front solutions $F_v(x - vt)$ with F_v decreasing, $F_v(x) \rightarrow 1$ as $x \rightarrow -\infty$, $F_v(x) \rightarrow 0$ as $x \rightarrow \infty$ and $F_v(x) \simeq e^{-\gamma x}$ for large x , with $v = \gamma + \gamma^{-1}$. For initial data $u_0(x) = \mathbf{1}(x \leq 0)$ we have convergence to the traveling front with minimal speed,

$$v_0 = 2 \quad (1.16)$$

in the sense that

$$\lim_{t \rightarrow \infty} \sup_{x \in \mathbf{R}} |u(t, x) - F_{v_0}(x - m^*(t))| = 0 \quad (1.17)$$

where $m^*(t)$ defined by $u(t, m^*(t)) = 1/2$ satisfies $\lim_{t \rightarrow \infty} m^*(t)/t = v_0$. Further details about convergence of the KPP solution to the traveling front were given by McKean [McK75] and [McK76], and Bramson [Bra78] and [Bra83], among many others.

When $\epsilon > 0$ with initial data in \mathcal{C}_{exp} satisfying (1.6), one has non-negative, continuous solutions, with a finite upper bound on the support

$$r(t) = \sup\{x \in \mathbf{R} : u(t, x) > 0\}, \quad (1.18)$$

for $t > 0$. The process viewed from $r(t)$,

$$\tilde{u}(t, x) = u(t, x + r(t)) \quad (1.19)$$

should have a unique nondegenerate stationary solution. This is the *random traveling front*. One also expects $t^{-1}r(t)$ to have a nonrandom limit,

$$v_\epsilon = \lim_{t \rightarrow \infty} t^{-1}r(t). \quad (1.20)$$

This was proved [MS95] in the case (1.9), (1.10), for sufficiently small ϵ . They consider initial data $0 \leq u_0(x) \leq 1$ such that $u_0(x) = 1$ for $x < \ell$ and $u_0 = 0$ for $x > r$ for some $-\infty < \ell \leq r < \infty$. Because in this case $\sigma(1) = 0$, solutions stays within this class, and the result of [MS95] extends to any f and σ satisfying in addition to our assumptions, that $\sigma(u) = 1 + \mathcal{O}(\sqrt{1-u})$ as $u \uparrow 1$.

We now make some comments to justify the form (1.4),(1.5) of the stochastic perturbation. The most important reason for taking

$$\sigma(u) \simeq \sqrt{u}, \quad 0 \leq u \ll 1 \quad (1.21)$$

is that this is the type of correction seen when approximating the reaction-diffusion problems by microscopic particle models. For example, the reaction-diffusion equation with $f(u) = u(1-u)$ was originally derived by Fisher as a model for the spread of an advantageous gene; the term $u(1-u)$ in (1.9) represents the frequency of mating between the individuals with and without the advantageous gene. If there is randomness in the mating, for example, if matings were successful with a certain probability, the variance of the random term is naturally proportional to $u(1-u)$, and this leads to a term $\sqrt{u(1-u)}\dot{W}(t, x)$.

In this article we are primarily concerned with the asymptotics of v_ϵ as $\epsilon \rightarrow 0$ in (1.1). It is not hard to see (for example, in (1.9), by taking expectations, and applying Jensen's inequality) that $v_\epsilon \leq v_0$. Recently, Brunet and Derrida [BD97] and [BD01] (see also [KS98], [PL99]) have made the remarkable conjecture that as $\epsilon \rightarrow 0$,

$$v_0 - v_\epsilon \simeq \frac{\pi^2}{|\log \epsilon^2|^2}. \quad (1.22)$$

It is worth noting how enormous the correction is. For example, a naive Taylor expansion might suggest, since symmetry implies $\epsilon = 0$ is a local maximum, that $v_0 - v_\epsilon \simeq \mathcal{O}(\epsilon^2)$. The phenomenon was unexpected, and first observed through computer simulations of particle systems. It was not long before this was understood at the physical level as a consequence of the pulled nature of the fronts. Recall that in an evolution equation with traveling fronts between an unstable and a stable state, the front is said to be *pulled* if its asymptotic speed is the same as that of the linearization of the equation about the unstable state, and *pushed* if the speed is larger than that of the linearization (see [vS]). KPP equations have (marginally) pulled fronts. Because in pulled fronts the front speed is determined in the region where the density u is very small, in retrospect one should not be surprised that fluctuations there of order \sqrt{u} , would have a dramatic effect on the front speed. Bramson [Bra78] also proved for the KPP equation with initial data $u_0(x) = \mathbf{1}(x \leq 0)$, that,

$$m^*(t) = v_0 t + \frac{3}{2} \log t + \mathcal{O}(1), \quad (1.23)$$

which is also supposed to be universal for pulled fronts [vS]. These behaviors all reflect the fact that in pulled fronts there is no spectral gap in the linearization around F_{v_0} .

The phenomenon (1.22) has also been observed in systems where the variable u is forced to take discrete values, such as particle systems on the lattice with random walks and birth-death components. Here ϵ^2 is the effective mass of a particle.

Brunet and Derrida [BD97] conjectured that the front speeds in these systems behave for small ϵ like that of the solution of the cutoff KPP equation

$$\partial_t u = \partial_x^2 u + u(1-u)\mathbf{1}(u \geq \epsilon^2). \quad (1.24)$$

The idea is that when $u < \epsilon^2$, $u(1-u) < \epsilon\sqrt{u(1-u)}$ and the noise term in (1.1) beats the creation term down to zero. Alternatively (1.24) can be thought of as a single particle cutoff. They then gave a nonrigorous argument that for small ϵ , (1.24) has travelling fronts with velocity

$$v_{\text{cutoff}} \simeq v_0 - \frac{\pi^2}{|\log \epsilon^2|^2}. \quad (1.25)$$

The argument for (1.25), using matched asymptotics, is not difficult to make rigorous. It is known [DPK], [BDL] that

$$v_{\text{cutoff}} - v_0 + \frac{\pi^2}{|\log \epsilon^2|^2} = \mathcal{O}\left(\frac{1}{|\log \epsilon|^3}\right). \quad (1.26)$$

Implicit in our argument is a simpler proof (with a slightly worse correction of $\mathcal{O}(\frac{\log |\log \epsilon|}{|\log \epsilon|^3})$).

What was less clear was how to make rigorous the connection between either microscopic particle models or (1.1) and (1.24). Here we work with (1.1) as a

kind of canonical model system for the phenomenon (1.22): In particular, the fact that particle models and (1.1) both are expected to display this behaviour is perhaps the strongest motivation for the particular form of the noise (1.5).

See [P] and references therein for a very comprehensive review of the physical aspects of the Brunet-Derrida theory.

Conlon and Doering [CD04] recently obtained progress on (1.22) by coupling (1.9), (1.10) to a contact process (see Liggett [Lig85]), proving that for sufficiently small ϵ ,

$$v_\epsilon \geq v_0 - \frac{C \log |\log \epsilon|}{|\log \epsilon|^2}. \quad (1.27)$$

Very recently, [BDMM] have made a conjecture about the corrections to (1.22). Using a phenomenological argument, they propose

$$v_\epsilon - v_0 + \frac{\pi^2}{|\log \epsilon^2|^2} \simeq \frac{6\pi^2 \log |\log \epsilon|}{|\log \epsilon^2|^3}. \quad (1.28)$$

The 6 on the right hand side is closely related to the 3 in (1.23).

In this article we prove the Brunet-Derrida conjecture for models of the form (1.1)-(1.3) with a correction of the same order as conjectured in [BDMM].

However our understanding of the well-posedness of (1.1) is not complete, and so a few comments are needed before we can state the result.

Existence for (1.1) is straightforward and can be obtained as the limit of its spatial discretization (1.15). Starting with non-negative initial data, one obtains in this way a non-negative solution, Hölder $\alpha < 1/2$ in space and $\beta < 1/4$ in time. Alternately, equations of the form (1.1) can be obtained as appropriate limits of particle systems. Note that we are allowing solutions to have $u \geq 1$, which is slightly non-standard, in particular for models such as $f(u) = \sigma^2(u) = u(1-u)$ where u is usually taken to be in $[0, 1]$. In terms of existence, this does not make any difference.

On the other hand, uniqueness of (1.1) is not known in our case because the coefficient in front of the noise is not Lipschitz. At the time of writing there is not even a consensus whether strong uniqueness should be true (for new results on strong uniqueness for stochastic partial differential equations with non-Lipschitz coefficients see [MP], although they still do not cover the present case). *Weak uniqueness* means uniqueness of the martingale problem for (1.1) with respect to the family of functionals $f_\phi(u) = \exp\{-\int u\phi dx\}$, ϕ smooth, non-negative, with compact support, within the class of continuous non-negative solutions u , and in addition, the measurability of the Markov transition functions $P_{s,u(\cdot)}(A) = P(u(t, \cdot) \in A \mid u(s, \cdot) = u(\cdot))$. Weak uniqueness in particular implies the strong Markov property, which is one of our basic tools. Weak uniqueness can be obtained in special cases of (1.1) using duality. An example is when σ is of the form (1.10) or (1.11). The case (1.9), (1.10) has an explicit dual particle system, described below, whose existence allows one in principle to compute the law for the stochastic partial differential equation. The case (1.9), (1.11) is self-dual (see [HT]).

What we really use about our solutions are the strong Markov property with respect to a family of hitting times, together with the *comparison principle*. Roughly the comparison principle for SPDE states that if u and v are solutions of

$$\partial_t u = \partial_x^2 u + f(x, u) + \sigma(u)\dot{W}, \quad \partial_t v = \partial_x^2 v + g(x, v) + \sigma(v)\dot{W} \quad (1.29)$$

on $[0, T]$ with $v(0, x) \leq u(0, x)$, and $g(x, u) \leq f(x, u)$ for all x, u , then $v(t, x) \leq u(t, x)$ for all $t \in [0, T]$ and $x \in \mathbf{R}$ almost surely. It is the analogue of monotonicity or attractiveness in particle systems. Examples of such theorems can be found in [Pa]. A simple variant of the above is that our v will, in addition, satisfy a Dirichlet condition $v = 0$ on a set U such as $x > vt$ or $|x| \geq vt + L$. This is not a large leap, as one can think of it as the $N \rightarrow \infty$ limit of $g = -N$ on U . So there is no surprise that the comparison continues to hold. There will be a few other twists and we will be a little more precise later. But the main point is that proofs of comparison theorems of this type require as input a strong uniqueness theorem. Hence they are not directly available to us.

Now any solution we are really interested in will be the result of some approximation scheme by systems, for example particle systems, for which the comparison principle is essentially obvious. Similarly, the strong Markov property will hold for such systems. And both are maintained under weak limits. So we could in principle just take a pragmatic approach and simply assume that our solution has the needed properties. Since this is a little cumbersome, instead we will state our results under the assumption of weak uniqueness.

Note that weak uniqueness implies the existence of versions satisfying both the strong Markov property and comparison principle. That it implies the strong Markov property is well known. To obtain a version satisfying the comparison principle, construct a sequence of Lipschitz $\sigma^{(n)}(u)$ converging uniformly to $\sigma(u)$. The corresponding equations have strong uniqueness and therefore the comparison principle. It is not hard to check that such sequences are tight and it is easy to see that the comparison principle continues to hold in the weak limits. Note that all our results are statements in distribution. It is therefore always enough to work with appropriate versions of our process, and therefore weak uniqueness is sufficient.

We can now state the main theorem. Let $u(t, x)$ be the solution of (1.1) and $r(t)$ be as in (1.18). For initial data in \mathcal{C}_{exp} satisfying (1.6) let

$$\bar{v}_\epsilon = \limsup_{t \rightarrow \infty} t^{-1} r(t). \quad (1.30)$$

For initial data satisfying $u(0, x) \geq \theta > 0$, $x \leq 0$, $u(0, x) = 0$, $x > 0$, let

$$\underline{v}_\epsilon = \liminf_{t \rightarrow \infty} t^{-1} r(t). \quad (1.31)$$

Let $\alpha(a)$ be the largest α such that

$$(1 - a)u1(u \leq \alpha) \leq f(u). \quad (1.32)$$

Note that $\alpha(a) > 0$ if $a > 0$ from the assumptions on f . For example, if $f''(0) > -\infty$ we have $\alpha(a) = Ca$ for some $C < \infty$.

Theorem 1.1. Assume $u_0(x) \in \hat{\mathcal{C}}$ satisfying (1.6), (1.7), (1.8). Then there exists $\epsilon_0 > 0$ such that for all $\epsilon \leq \epsilon_0$,

$$\underline{v}_\epsilon \geq v_0 - \frac{\pi^2}{|\log \epsilon^2|^2} - \frac{2\pi^2[9 \log |\log \epsilon| - \log \alpha(|\log \epsilon|^{-3})]}{|\log \epsilon^2|^3} \quad (1.33)$$

$$\bar{v}_\epsilon \leq v_0 - \frac{\pi^2}{|\log \epsilon^2|^2} + \frac{8\pi^2 \log |\log \epsilon|}{|\log \epsilon^2|^3}. \quad (1.34)$$

Remark on ϵ_0 . Since the phenomena is observed in particle simulations, it is worthwhile to ask whether the mathematical result can be proven with ϵ_0 of a size approachable by computation. In fact, computations with effectively $N = 10^{10}$ particles are commonplace at the time of writing. In case (1.9), (1.10), we can check that our method works with $\epsilon_0 = e^{-11}$. Since N particles corresponds to a correction of size $\epsilon = N^{-1/2}$ the mathematical result covers the typical regime of computations.

Remark on duality for the case of (1.1) with $f(u) = \sigma(u) = u(1-u)$. Let $x_i(t) : i = 1, \dots, N(t) \leq \infty$ be a system of independent Brownian motions with generators ∂_x^2 . Each particle splits in two at rate 1, and pairs of particles coalesce at exponential rate ϵ^2 during their intersection local time. The generator is

$$Af(\mathbf{x}) = \sum_i \Delta_i f(\mathbf{x}) + \sum_i (f(\mathbf{x}_i^+) - f(\mathbf{x})) + \epsilon^2 \sum_{i>j} \delta_{x_i=x_j} (f(\mathbf{x}_i^-) - f(\mathbf{x})) \quad (1.35)$$

where \mathbf{x}_i^+ is the configuration obtained from \mathbf{x} by replacing x_i by two particles at the same location, and \mathbf{x}_i^- is the configuration obtained from \mathbf{x} by removing x_i . We have the duality relation [Shi88],

$$E \left[\prod_i (1 - u(t, x_i(0))) \right] = E \left[\prod_i (1 - u(0, x_i(t))) \right], \quad (1.36)$$

where the expectation is taken over independent u and x_i . Among other things, (1.36) gives us an expression for the moments of u , providing the weak uniqueness.

One can also deduce from the result about the wavespeed in the random KPP results about the wavespeed in the dual process. Suppose we start our branching and coalescing system with one particle at 0, and let $L(t)$, $R(t)$ denote the positions of the leftmost and rightmost particles in the system at time t . Take $u_0(x) = \mathbf{1}(x \leq 0)$. The duality relation, together with the natural reflection symmetry and spatial homogeneity, give $P(L(t) < -x) = P(R(t) > x) = E[u(t, x)]$, and Theorem 1.1 then translates to

$$\lim_{t \rightarrow \infty} t^{-1} R(t) = - \lim_{t \rightarrow \infty} t^{-1} L(t) = v_\epsilon. \quad (1.37)$$

Here then is another example of the Brunet-Derrida theory: The branching-coalescing Brownian motions model possesses two invariant measures. The stable one is a Poisson point process with intensity ϵ^{-2} , and the unstable one

consists of no particles at all. On a large scale we see the first invading the second at linear speed v_ϵ . If we introduce a phase variable in $[0, 1]$ so that 0 corresponds to the unstable phase and 1 corresponds to the stable phase, then the effective particle mass is ϵ^2 , as predicted.

Finally we comment on the structure of the paper. To make the arguments leading to Theorem 1.1 more transparent, in the next section we sketch the logic of the proof, assuming the main technical lemmas, which are then left for later sections, and assuming as well that the necessary manipulations of the SPDEs can be performed. We then prove the validity of these manipulations in Section 3.

2 Outline of the proof

2.1 Comparison equation

The general idea behind our proof of Theorem 1.1 is to compare the stochastic KPP evolution (1.1) to:

$$\begin{cases} \partial_t \varrho = \partial_x^2 \varrho + f(\varrho), & x < vt, \\ \varrho(t, x) = 0, & x \geq vt. \end{cases} \quad (2.1)$$

We search for the $v = v_{\text{com}}$ for which there exists a traveling front solution

$$\varrho(x, t) = F(x - v_{\text{com}}t) \quad (2.2)$$

with $\lim_{x \rightarrow -\infty} F(x) = 1$ and

$$F'(0) = -\varepsilon^2. \quad (2.3)$$

The problem (2.1)-(2.3) is our replacement for Brunet and Derrida's comparison equation (1.24). The idea is that the solution will have a mass of $\mathcal{O}(\varepsilon^2)$ within a distance $\mathcal{O}(1)$ of $x = v_{\text{com}}t$. Here ε is a small parameter which does not necessarily have to be related to the perturbation parameter ϵ in (1.1). In fact, it will be convenient to take ε to be slightly larger or smaller than ϵ . But if $\varepsilon = \epsilon$, the mass $\mathcal{O}(\varepsilon^2)$ is the critical mass which can survive in the stochastic equation when u is small. Heuristically, this will provide a consistent strategy for a stochastic traveling front in (1.1) to propagate.

To determine the resulting $v = v_{\text{com}}(\varepsilon^2)$, let $\mathbf{x}(t) = F(-t)$ and note that the problem is equivalent to that of finding the v such that the solution of the ordinary differential equation

$$\mathbf{x}'' = v\mathbf{x}' - f(\mathbf{x}), \quad \mathbf{x}(0) = 0, \quad \mathbf{x}'(0) = \varepsilon^2 \quad (2.4)$$

has $\mathbf{x}(\infty) = 1$. Let $\mathbf{y} = \mathbf{x}'$. In the phase plane of

$$\begin{aligned} \mathbf{x}' &= \mathbf{y} \\ \mathbf{y}' &= v\mathbf{y} - f(\mathbf{x}) \end{aligned} \quad (2.5)$$

there is an unstable node at $(\mathbf{x}, \mathbf{y}) = (0, 0)$ and a saddle point at $(\mathbf{x}, \mathbf{y}) = (1, 0)$, joined by a separatrix solution $(\mathbf{x}(t), \mathbf{y}(t))$, $-\infty < t < \infty$, with $\mathbf{x}(-\infty) = 0$, $\mathbf{x}(\infty) = 1$. For $v \geq 2$, the linearization $\mathbf{x}'_{\text{lin}} = \mathbf{y}_{\text{lin}}$, $\mathbf{y}'_{\text{lin}} = v\mathbf{y}_{\text{lin}} - \mathbf{x}_{\text{lin}}$ about $(0, 0)$ has distinct positive eigenvalues which merge as $v \downarrow 2$, then split into a complex pair for $v < 2$. For $v \geq 2$, the separatrix corresponds to an exponentially decaying traveling front solutions of the (nonrandom) KPP equation. For $v < 2$, $(0, 0)$ is a spiral source, the $\mathbf{x} \geq 0$ corresponding in the same way to a traveling front solutions of (2.1). The separatrix enters the region $(\mathbf{x}, \mathbf{y}) \in (0, 1) \times (0, \infty)$ at $(\mathbf{x}, \mathbf{y}) = (0, \varepsilon^2(v))$, and problem (2.1)-(2.3) is now seen to be equivalent to computing the inverse function $v(\varepsilon^2)$.

Proposition 2.1. *Let $v_{\text{com}} = v_{\text{com}}(\varepsilon^2)$ be the solution of (2.1)-(2.3). There exist $\varepsilon_0 > 0$ such that for $|\varepsilon| < \varepsilon_0$,*

$$2 - \frac{\pi^2}{(|\log \varepsilon^2| - 3 \log |\log \varepsilon^2| - \log \alpha(|\log \varepsilon^2|^{-3}) - 2)^2} \leq v_{\text{com}} \leq 2 - \frac{\pi^2}{(|\log \varepsilon^2| + 3)^2}. \quad (2.6)$$

If $\alpha(a) = a$ then ε_0 can be taken to be e^{-8} .

First we give the heuristic idea of the proof. It is not hard to see that $v(\varepsilon^2)$ is monotone decreasing in ε with $v \downarrow 2$ as $\varepsilon^2 \downarrow 0$. The linearization about $(0, 0)$ has explicit solution

$$\mathbf{x}_{\text{lin}}(t) = \varepsilon^2 \hat{\delta}^{-1/2} \exp\{(1 - \frac{\delta}{2})t\} \sin(\hat{\delta}^{1/2}t) \quad (2.7)$$

where

$$\delta = 2 - v. \quad (2.8)$$

and $\hat{\delta} = \delta - \frac{\delta^2}{4}$. Let Θ be the smallest $t > 0$ with

$$\mathbf{x}_{\text{lin}}(\Theta) = 1. \quad (2.9)$$

Note that $\Theta \sim |\log \varepsilon^2|$. Pretending the linearization is meaningful globally, one would want

$$\mathbf{x}'_{\text{lin}}(\Theta) = 0. \quad (2.10)$$

(2.9) and (2.10) become, with $C_1 = 1$, $C_2 = (1 - \frac{\delta}{2})$,

$$\begin{aligned} \varepsilon^2 \hat{\delta}^{-1/2} \exp\{(1 - \frac{\delta}{2})\Theta\} \sin(\hat{\delta}^{1/2}\Theta) &= C_1 \\ \varepsilon^2 \exp\{(1 - \frac{\delta}{2})\Theta\} (-\cos(\hat{\delta}^{1/2}\Theta)) &= C_2. \end{aligned} \quad (2.11)$$

(2.11) gives a nonlinear equation for δ in terms of ε from which it is simple to obtain estimates like (2.6). The only difference in the rigorous proof is that we will use sub- and super-solutions to get (2.11), but with slightly worse C_1 and C_2 .

Proof of Proposition 2.1. First of all note that $v = v_{\text{com}}$ depends monotonically on f : If $f_1(u) \leq f_2(u)$ for all u then the corresponding $v(f_1) \leq v(f_2)$.

Upper bound. Consider (2.1)-(2.3) with f replaced by

$$\bar{f}(u) = \begin{cases} u & \text{if } u \in [0, 1] \\ 2 - u & \text{if } u > 1. \end{cases} \quad (2.12)$$

The corresponding $v = v_{\text{com}}$ is larger as $\bar{f} \geq f$. Call $\delta = 2 - v$ and assume momentarily that $\delta < 0.2$. The solution to

$$\mathbf{x}'' = v\mathbf{x}' - \bar{f}(\mathbf{x}), \quad (2.13)$$

can be computed explicitly. For $t \leq \Theta = \inf\{t > 0 : \mathbf{x}(\Theta) = 1\}$, $\mathbf{x}(t) = \mathbf{x}_{\text{lin}}(t)$ from (2.7). Now we consider the phase plane $(\mathbf{x}, \mathbf{x}')$. One checks that the linearization around the saddle $(\mathbf{x}, \mathbf{x}') = (2, 0)$ has stable direction $(\varpi, 1)$ and unstable direction $(\lambda, 1)$ where,

$$\varpi(\delta) = 1 - \frac{\delta}{2} - (2 - \delta)^{1/2}, \quad \lambda = 1 - \frac{\delta}{2} + (2 - \delta)^{1/2}. \quad (2.14)$$

A separatrix solution $(\mathbf{x}, \mathbf{x}')$ joins $(0, \varepsilon^2)$ to $(2, 0)$. It must coincide with the stable line $y = \varpi x - 2\varpi$ in the region $\mathbf{x} > 1$, because the equation is linear there. So in order for $(\mathbf{x}(\Theta), \mathbf{x}'(\Theta))$ to lie on the separatrix we must have

$$\mathbf{x}'_{\text{lin}}(\Theta) = \varpi \mathbf{x}_{\text{lin}}(\Theta) - 2\varpi, \quad (2.15)$$

which is equivalent to (2.11), with $C_1 = 1$ and $C_2 = -\varpi$.

Lower bound. Let $\alpha = \alpha(|\log \varepsilon^2|^{-3})$ from (1.32) and $a = 1 - 2|\log \varepsilon^2|^{-3}$ and define

$$\tilde{f}(u) = \begin{cases} au & \text{if } u \leq \alpha/2 \\ a(\frac{\alpha}{2} - u) & \text{if } u > \alpha/2. \end{cases} \quad (2.16)$$

Consider the problem (2.1)-(2.3) with f replaced by \tilde{f} . The corresponding $v = v(\tilde{f})$ is smaller than v_{com} because $\tilde{f} \leq f$. Call $\delta = 2 - v$. From the upper bound we know that for sufficiently small ε^2 , $\hat{\delta} = \delta - \frac{\delta^2}{4} > 0$, in which case the solution of

$$\mathbf{x}'' - v\mathbf{x}' + \tilde{f}(\mathbf{x}) = 0 \quad (2.17)$$

with $\mathbf{x}(0) = 0$ and $\mathbf{x}'(0) = \varepsilon^2$ is $\mathbf{x}(t) = \mathbf{x}_{\text{lin}}(t)$ from (2.7) for $t \leq \Theta$ when $\mathbf{x}_{\text{lin}}(\Theta) = \alpha/2$. In order to lie on the separatrix joining the unstable fixed point $(\mathbf{x}, \mathbf{x}') = (0, \varepsilon^2)$ to the saddle point $(\alpha, 0)$, we must have $(\mathbf{x}(\Theta), \mathbf{x}'(\Theta))$ on the stable line $y = (1 - \sqrt{2-a})(x - \alpha)$. This gives (2.11) with $C_1 = \alpha/2$ and $C_2 = (\sqrt{2-a} - 1 - \frac{\delta}{2})\alpha/2$.

Proof of (2.6). Assume ε_0 is sufficiently small that $\delta < 1$ and. Dividing the two equations in (2.11) gives $-\tan(\hat{\delta}^{1/2}\Theta) = \hat{\delta}^{1/2}(C_1/C_2)$. Let $\Theta = \hat{\delta}^{-1/2}\pi - \beta$. Since $\frac{4}{\sqrt{2\pi}}x \leq \tan x \leq \sqrt{2}x$ if $x \leq \pi/4$ the solution has $0 \leq C_1/(\sqrt{2}C_2) \leq \beta \leq \pi/4$. Now the second equation of (2.11) gives,

$$\hat{\delta}(1 - \frac{\delta}{2})^{-2} = \pi^2(|\log \varepsilon^2| + \log C_2 + |\log \cos(\hat{\delta}^{1/2}\beta)| + \beta)^{-2} \quad (2.18)$$

To get a lower bound on $v_{\text{com}} = 2 - \delta$, drop the non-negative terms $|\log \cos(\hat{\delta}^{1/2}\beta)|$ and β from the right hand side and note that $\delta \leq \hat{\delta}(1 - \frac{\delta}{2})^{-2}$ and $\log C_2 =$

$\log\{(\sqrt{2-a}-1)\alpha/2\} \geq -|\log \alpha| - 3\log|\log \varepsilon^2| - 2\log 2$. To get an upper bound, note first that if ε_0 is sufficiently small, then from the lower bound we have just described, $\hat{\delta} \leq 1$. Since $\beta \leq \pi/4$, we then have $|\log \cos(\hat{\delta}^{1/2}\beta)| \leq 1$. Also $\log C_2 = \log(\sqrt{2-\hat{\delta}}-1-\delta/2) < 0$. Finally, if we take ε_0 sufficiently small, then the lower bound we just proved gives $\delta < 10|\log \varepsilon^2|^{-2}$ so that $\hat{\delta}(1-\frac{\delta}{2})^{-2} \geq \delta(1+10|\log \varepsilon^2|^{-2})^{-1}$ and then (2.18) gives

$$\delta \geq \pi^2(|\log \varepsilon^2| + 2)^{-2} - 100|\log \varepsilon^2|^{-4} \quad (2.19)$$

which gives (2.6) for ε_0 small enough. \square

2.2 Upper bound

Consider u satisfying (1.1) with initial data

$$u(0, x) = \bar{F}(x) \quad (2.20)$$

where $\bar{q}(t, x) = \bar{F}(x - vt)$ is a traveling front solution of

$$\begin{cases} \partial_t \bar{q} = \partial_x^2 \bar{q} + \bar{f}(\bar{q}), & x < vt, \\ \bar{q}(t, x) = 0, & x \geq vt, \end{cases} \quad (2.21)$$

with \bar{f} as in (2.12),

$$v = v_{\text{com}}(\varepsilon^2) + |\log \varepsilon|^{-3} \quad (2.22)$$

and

$$-\bar{F}'(0) = \varepsilon^2 = \gamma \varepsilon^2 \quad (2.23)$$

with $0 < \gamma \ll 1$ to be chosen.

\bar{F} is a modified version of a traveling front from the comparison problem (2.1)-(2.3), with a larger $\bar{f} > f$, a slightly larger speed, and lying slightly above the separatrix connecting $(0, 0)$ to $(2, 0)$. There is some convenience in using \bar{f} instead of f . It is convex. Also, some things are explicitly computable. For example,

$$\bar{F}(x) = \begin{cases} 0, & x \geq 0; \\ \mathbf{x}_{\text{lin}}(-x), & -\Theta \leq x < 0; \\ \kappa \lambda e^{-\lambda(\Theta+x)} + 2 - (1 + \kappa)e^{-\varpi(\Theta+x)}, & x < -\Theta, \end{cases} \quad (2.24)$$

where $\kappa = \kappa(\varepsilon^2)$ is chosen such that F and F' are continuous at $x = -\Theta$ and \mathbf{x}_{lin} and Θ are defined in (2.7)-(2.10). Keep in mind that these all depend on ε though the dependence is not written explicitly. One can check that $\kappa \simeq (1 - 2^{-1/2})|\log \varepsilon^2|^{-2}$. Note also that the modification of the speed in (2.22) is smaller than the $\mathcal{O}(\frac{\log |\log \varepsilon|}{|\log \varepsilon|^3})$ error terms in the main result, Theorem 1.1.

Fix a positive integer T and an $L > 0$ and consider the hitting time

$$\xi = \inf\{t \in [0, T] : u(t, x) \geq \bar{F}(x - vt - L) \text{ for some } x \in \mathbf{R}\} \quad (2.25)$$

We run u up to time ξ , and then restart with new initial data

$$\bar{F}(x - v\xi - L), \quad (2.26)$$

a shift of L from the original comparison front. By the strong Markov property and the comparison theorem (Proposition 3.1), we obtain an upper bound \bar{u} on the original solution of (1.1) with initial data \bar{F} . Repeating the process, we inductively define a sequence of stopping times $\xi_{i+1} \in [\xi_i, \xi_i + T]$, and an upper bound \bar{u} for all time on the solution u with initial data $\bar{F}(x)$. \bar{u} satisfies (1.1) on (ξ_i, ξ_{i+1}) with initial data $u(\xi_i, x) = \bar{F}(x - v\xi_i - Li)$.

Suppose we can show that

$$P(\xi < T) < 1/2. \quad (2.27)$$

By the law of large numbers, the speedup of the front of \bar{u} over that of u is by a factor $L/E[\xi]$. But from (2.27), $E[\xi] \geq T/2$. We obtain in this way, using (2.6), (2.22) an upper bound on \bar{v}_ϵ defined in (1.30),

$$\begin{aligned} \bar{v}_\epsilon &\leq v + 2T^{-1}L \\ &\leq 2 - \pi^2 (\log \epsilon^{-2} + 3)^{-2} + |\log \epsilon|^{-3} + 2T^{-1}L. \end{aligned} \quad (2.28)$$

If we choose

$$T^{-1}L \leq |\log \epsilon|^{-3} \quad (2.29)$$

we obtain the upper bound (1.34) for initial data bounded above by \bar{F} .

There is a tradeoff between T and L . Large L in principle makes (2.27) easier, because $\bar{F}(x - vt - L)$ is increasing in L . But then (2.29) forces us to choose T large, and it becomes harder to control u on the long time interval to obtain (2.27).

For more general initial data, satisfying only $\int_0^\infty u_0(x)dx < \infty$, we can use the fact that at any time $t > 0$, $r(t) < \infty$ a.s. This is proved in the special case $\sigma^2(u) = u$ in [MP92], but it is well-known that the method can be adapted without too much work to cover the present situation. We do not give details here. This means that we can bound $u(t, \cdot)$ by a shift of \bar{F} , and obtain the upper bound (1.34) as before.

This reduces the upper bound to (2.27). The main idea to prove (2.27) is to split the solution $u(t, x)$ of (1.1) with initial data \bar{F} into

$$u = v + w \quad (2.30)$$

where $v(t, x)$ is the mass which does not cross $x = vt$;

$$\begin{cases} \partial_t v = \partial_x^2 v + f(v) + \epsilon \sigma(v) \dot{W}_1, & x < vt, \\ v(t, x) = 0, & x \geq vt, \end{cases} \quad (2.31)$$

with $v(0, x) = \bar{F}(x)$, and $w \geq 0$ is the rest. \dot{W}_1 will be another space-time white noise. As usual, the SPDE is interpreted in the mild sense;

$$\begin{aligned} v(t, x) &= \int G_v(0, y, t, x) \bar{F}(y) dy + \int \int_0^t G_v(s, y, t, x) f(v(s, y)) ds dy \\ &\quad + \epsilon \int \int_0^t G_v(s, y, t, x) \sigma(v(s, y)) W_1(ds dy) \end{aligned} \quad (2.32)$$

where $G_v(s, y, t, x)$ is the sub-probability density for a Brownian motion with generator ∂_x^2 , starting at y at time s , to end at x at time $t > s$ never having entered the region $\{z \geq vu\}$ for times $s \leq u \leq t$. In Proposition 3.1 in Section 3 it is shown that we can find a probability space on which such a splitting holds.

We expect the solution $v(t, x)$ of (2.31) to remain close to the solution $\varrho(t, x)$ of the deterministic comparison equation (2.1) with the same initial data $\bar{F}(x)$. Because it is a subsolution of (2.21) we have $\varrho(t, x) \leq \bar{F}(x - vt)$. If L is large enough, we can therefore expect v not to hit $\bar{F}(x - vt - L)$ for some time.

The key point now is that if $F'(0) \ll \epsilon^2$ then w is so negligible that $u = v + w$ does not hit $\bar{F}(x - vt - L)$ for some time either. To prove this, we need a better way to represent w . One can also view the Dirichlet boundary condition in (2.31) as a removal of mass. Let $A(t)$ be the mass which is removed at the boundary $x = vs$ in (2.31) during the time interval $0 \leq s \leq t$. Then we have another representation for v satisfying (2.31) or (2.32):

$$\partial_t v = \partial_x^2 v + f(v) + \epsilon \sigma(v) \dot{W}_1 - \delta_{x=vt} \dot{A}. \quad (2.33)$$

We would like to write an equation for w , with a new white noise \dot{W}_2 , independent of \dot{W}_1 . If \dot{W}_1 and \dot{W}_2 are independent white noises, then

$$\sigma_1 \dot{W}_1 + \sigma_2 \dot{W}_2 = \sqrt{\sigma_1^2 + \sigma_2^2} \dot{W} \quad (2.34)$$

where \dot{W} is a white noise. Hence the equation for w should read,

$$\partial_t w = \partial_x^2 w + f(v + w) - f(v) + \epsilon \tilde{\sigma} \dot{W}_2 + \delta_{x=vt} \dot{A}, \quad (2.35)$$

with initial data $w(0, x) \equiv 0$, where

$$\tilde{\sigma}(t, x, w) = \sqrt{\sigma^2(v(t, x) + w) - \sigma^2(v(t, x))}. \quad (2.36)$$

But this is only reasonable as long as $\sigma^2(v(t, x) + w) - \sigma^2(v(t, x))$ remains non-negative. In Proposition 3.1 of Section 3, it is shown that there exists a probability space on which there are white noises W_1 and W_2 for which (2.35) holds, up to a stopping time

$$\tau = \inf\{t \geq 0 : \exists x, \tilde{\sigma}(t, x, w(t, x)) = 0, w(t, x) \neq 0\}, \quad (2.37)$$

after which the desired noise coefficient $\tilde{\sigma}$ might cease to make sense.

By the comparison theorem, and since $f(v + w) - f(v) \leq \|f\|_{\text{Lip}} w$, up to time τ we have $u - v = w \leq \bar{w}$ almost surely, where

$$\partial_t \bar{w} = \partial_x^2 \bar{w} + \|f\|_{\text{Lip}} \bar{w} + \epsilon \tilde{\sigma}(\bar{w}) \dot{W}_2 + \delta_{\{x=vt\}} \dot{A}. \quad (2.38)$$

As long as

$$\tilde{\sigma}^2(\bar{w}) \geq a^* \bar{w}, \quad (2.39)$$

this is basically a superprocess with an injection of mass at $\{x = vt\}$. The critical input of mass in such an equation is easily calculated to be $\mathcal{O}(\epsilon^2)$. In

other words, if the rate of mass entering is $o(\epsilon^2)$, then it is being killed by the noise in time $\mathcal{O}(1)$ with very high probability. And it suffices to show just that the *expected* incoming mass $E[A(t+1) - A(t)]$ is $o(\epsilon^2)$.

To get such a bound, note that by comparison $v \leq \bar{v}$, the solution of

$$\partial_t \bar{v} = \partial_x^2 \bar{v} + \bar{f}(\bar{v}) + \epsilon \sigma(\bar{v}) \dot{W}, \quad x \leq vt \quad (2.40)$$

with $\bar{v} = 0$ for $x \geq vt$. Take expectation in (2.40) and use the concavity of \bar{f} to see that $E[v]$ is a subsolution of (2.21). In particular,

$$E[v(t, x)] \leq \bar{F}(x - vt). \quad (2.41)$$

This can be translated into a bound on the expected rate of incoming mass $A(t)$ as follows. Taking expectation in (2.33),

$$\begin{aligned} E[A(t+1) - A(t)] &= \int q(t, y, t, t+1) E[v_t(y)] dy \\ &\quad + \int \int_t^{t+1} q(s, y, s, t+1) E[f(v(s, y))] ds dy \end{aligned} \quad (2.42)$$

where $q(s, y, u, t) = P_{s,y}(\exists r \in (u, t] : B_r \geq vr)$ for a Brownian motion B_r with generator ∂_x^2 . Using $E[f(v)] \leq E[\bar{f}(v)] \leq \bar{f}(E[v]) \leq \bar{f}(\bar{\rho})$, and that $v_0(y) = \bar{F}(y)$, we see that

$$\begin{aligned} E[A(t+1) - A(t)] &\leq \int q(t, y, t, t+1) \bar{F}(y - vt) dy \\ &\quad + \int \int_t^{t+1} q(s, y, s, t+1) \bar{f}(\bar{F}(y - vs)) ds dy. \end{aligned} \quad (2.43)$$

Now $\bar{F}(x - vt)$ is a traveling front solution of (2.1) with \bar{f} instead of f . The rate of mass removal at the boundary is proportional to the slope ϵ^2 at the boundary, and hence there is a $C_{(2.44)} < \infty$ such that,

$$E[A(t+1) - A(t)] \leq C_{(2.44)} \epsilon^2. \quad (2.44)$$

The only difficulty is maintaining (2.39). By (1.5) it holds as long as $v + \bar{w} \leq u^*$. What we will do is obtain an a priori estimate that $v \leq u^*/2$ in a strip $vt - M \leq x \leq vt$. This is reasonable since we know that v is close to ρ , which is of $\mathcal{O}(\epsilon^2)$ there. If

$$M = M(u^*) \quad (2.45)$$

is chosen sufficiently large, we can then iteratively show that $\bar{w} \leq u^*/2$, and furthermore that it does not support the complement of a strip $vt-1 \leq x \leq vt+1$ around our proposed front. This then provides us with sufficient noise to show that w is negligible there as well.

To fix γ and T , let us explain very briefly the iterative procedure. Take T to be an integer and divide up the time interval $[0, T]$ into intervals of length 1. The mass arriving in $[n, n+1)$ and evolving according to (2.38), is bounded

by (2.44). It dies before time $n + 2$ with probability at least $1 - c_0\gamma$ where $c_0 = c_0(a^*, \|f\|_{\text{Lip}})$. So this happens for every $n = 0, 1, 2, \dots, T - 1$, with probability at least

$$1 - c_0\gamma T. \quad (2.46)$$

In order to have the probability in (2.46) greater than $\frac{3}{4}$, we thus take

$$\gamma = \frac{1}{4}c_0^{-1}T^{-1}. \quad (2.47)$$

To fix all our constants we note that if

$$L = |\log \epsilon| + \log |\log \epsilon| \quad (2.48)$$

then we have

$$F(x - L) \geq F(x) + 3\lambda e^{-\lambda x}. \quad (2.49)$$

By (2.29) we need

$$T = \lfloor |\log \epsilon|^4 \rfloor. \quad (2.50)$$

We have explained how the upper bound is a consequence of the following lemmas.

Lemma 2.2. *Let v be the solution of (2.31) with initial data (2.24). Let ϱ be the solution of (2.21) with the same initial data. Let γ, L, T, M be as in (2.45)-(2.50). Then*

$$P\left(\exists t \in [0, T] : v(t, x) > \bar{\varrho}(t, x) + 3\lambda e^{-\lambda(x-vt)} \text{ for some } x \in \mathbb{R}\right) \leq 1/16. \quad (2.51)$$

Lemma 2.3. *Under the same conditions as in Lemma 2.2,*

$$P(\exists t \in [0, T] : v(t, x) > u^*/2 \text{ for some } x \in (vt - M, vt)) \leq 1/8. \quad (2.52)$$

Lemma 2.4. *Under the same conditions as in Lemma 2.2, let \bar{w} be the solution of (2.38) where A is defined in (2.33)*

$$P(\exists t \in [0, T] : \sup_{x \in [vt-1, vt+1]^c} \bar{w}(t, x) > 0 \text{ or } \sup_{x \in [vt-1, vt+1]} \bar{w}(t, x) \geq u^*/2) \leq 1/4. \quad (2.53)$$

2.3 Lower bound

The proof of the lower bound uses a more standard method; comparison to oriented percolation [BraDurr88]. Similar arguments were used by Conlon and Doering [CD04] to prove their lower bound. The improvement here comes from the use of the special comparison front from (2.17) and refined large deviation estimates.

For $v, L > 0$ let $G_{v,L}(s, y, t, x)$ be the sub-probability density in x at time t for a Brownian motion B_u , $s \leq u \leq t$ with generator ∂_x^2 , starting at $B_s = y$,

killed if it enters the region $|z| \geq vu + L$, $s \leq u \leq t$. If $\varrho(t, x)$ is a given function, let

$$(\mathcal{G}\varrho)(t, x) = \int \int_0^t G_{v,L}^2(s, y, t, x) \varrho(s, y) ds dy \quad (2.54)$$

Note that this makes sense since we are in one dimension. The lower bound is based on the following simple lemma about the deterministic equation. Let

$$\underline{f}(u) = \begin{cases} (1 - |\log \epsilon|^{-3})u & \text{if } u \leq \alpha/2 \\ (1 - |\log \epsilon|^{-3})(\frac{\alpha}{2} - u) & \text{if } u > \alpha/2. \end{cases} \quad (2.55)$$

From the definition (1.32) of α , we have

$$\underline{f}(u) \leq f(u) \quad \text{whenever } f(u) \geq 0. \quad (2.56)$$

Let

$$\varepsilon^2 = \gamma \epsilon^2 \quad (2.57)$$

with $1 \ll \gamma$ and $v = v_{\text{com}}(\varepsilon)$ as in (2.1) - (2.3).

Lemma 2.5. *There exist $\epsilon_0 > 0$, $C_{(2.59)} < \infty$, $0 < L \leq |\log \epsilon|$, and $\underline{\varrho}_0(x)$ supported on $[-L, L]$ with $0 \leq \underline{\varrho}_0(x) \leq \alpha(|\log \epsilon^2|^{-3})$ such that if $\epsilon < \epsilon_0$, $\gamma \geq C_{(2.59)}|\log \epsilon|^{10}$ and $r > 1$, the solution $\underline{\varrho}(t, x)$ on $0 \leq t \leq 1$ of*

$$\begin{cases} \partial_t \underline{\varrho} = \partial_x^2 \underline{\varrho} + \underline{f}(\underline{\varrho}), & |x| < L + vt \\ \underline{\varrho}(t, x) = 0, & |x| \geq L + vt, \end{cases} \quad (2.58)$$

with $\underline{\varrho}(0, x) = \underline{\varrho}_0(x)$, and \underline{f} as in (2.55), satisfies, for $v' = v + |\log \epsilon|^{-3}$,

$$\underline{\varrho}(1, x) - r\epsilon\sqrt{\mathcal{G}\underline{\varrho}(1, x)} \geq \underline{\varrho}_0(x - v') \quad x \in [v' - L, v' + L]. \quad (2.59)$$

Proof. We follow the notation and construction from the proof of the lower bound of Proposition 2.1. Let α , a , \mathbf{x} and Θ all be as in the proof of the lower bound of Proposition 2.1. We claim that (2.59) holds with $L = \Theta$ and

$$\underline{\varrho}_0(x) = \begin{cases} \mathbf{x}(L - |x|) & 0 \leq |x| < L, \\ 0 & |x| \geq L. \end{cases} \quad (2.60)$$

To prove this, note that the solution $\underline{\varrho}(t, x)$ of (2.58) satisfies $\underline{\varrho}(t, x) \leq \bar{q}(t, x) = e^{t|\log \epsilon|^{-3}} \min\{\mathbf{x}(L + vt - x), \mathbf{x}(L)\}$ since $\underline{\varrho}_0(x) \leq \mathbf{x}(L - x)$, $x \in \mathbf{R}$, and $\bar{q}(t, x)$ is a supersolution of (2.58), and $\underline{\varrho}(t, x) \geq \underline{q}(t, x)$ where

$$\underline{q}(t, x) = \begin{cases} e^{t|\log \epsilon|^{-3}} \mathbf{x}(L + vt - |x|) & vt \leq |x| < L + vt \\ e^{t|\log \epsilon|^{-3}} \mathbf{x}(L) & |x| \leq vt \\ 0 & |x| \geq vt + L \end{cases} \quad (2.61)$$

since $\underline{q}(t, x)$ is a subsolution of (2.58) with the same initial data. So

$$\begin{aligned} \underline{\varrho}(1, x) - \underline{\varrho}_0(x - v') &\geq \underline{q}(1, x) - \underline{\varrho}_0(x - v') \\ &\geq \begin{cases} \mathbf{x}_{\text{lin}}(L + v - |x|) - \mathbf{x}_{\text{lin}}(L + v' - |x|) & |x| \in (v, v' + L], \\ (e^{|\log \epsilon|^{-3}} - 1)\mathbf{x}_{\text{lin}}(L) & |x| \leq v, \end{cases} \end{aligned} \quad (2.62)$$

Here we used that $\mathbf{x}(t) = \mathbf{x}_{\text{lin}}(t)$ for $t \leq L$. For $|x| \in (v, v' + L]$ we now use that if $\delta < 1/2$ then $\mathbf{x}'_{\text{lin}} \geq \varepsilon^2 e^{\frac{1}{2}(L+v-|x|)}$ there and $v - v' = |\log \epsilon|^{-3}$ to get a lower bound. For $|x| \geq v$ we use $e^{|\log \epsilon|^{-3}} - 1 \geq |\log \epsilon|^{-3}$ and $\mathbf{x}_{\text{lin}}(L) = \alpha/2$. This gives

$$\underline{\varrho}(1, x) - \underline{\varrho}_0(x - v') \geq \begin{cases} |\log \epsilon|^{-3} \varepsilon^2 e^{\frac{1}{2}(1-\frac{\delta}{2})(L+v-|x|)} & |x| \in (v, v' + L], \\ |\log \epsilon|^{-3} \alpha/2 & |x| \leq v, \end{cases} \quad (2.63)$$

From the explicit form of \mathbf{x}_{lin} , and using $G_{v,L} \leq G$, as long as $\exp\{|\log \epsilon|^{-3}\} \leq 2$ and $\delta < 1$,

$$\begin{aligned} (\mathcal{G}\bar{q})(1, x) &\leq 2 \int_0^1 \int_{-\infty}^{vs} \frac{e^{-\frac{(y-x)^2}{2(1-s)}}}{4\pi(1-s)} \min\{\varepsilon^2 \delta^{-1/2} e^{vs-y+L}, \alpha/2\} ds dy \\ &\leq \min\{4\varepsilon^2 \delta^{-1/2} e^{-(x-L-v)}, \alpha\}. \end{aligned} \quad (2.64)$$

Hence one can check that $\underline{\varrho}(1, x) - \underline{\varrho}_0(x - v') \geq r\epsilon\sqrt{\mathcal{G}\bar{q}}$ as long as

$$r \leq \min\{6\gamma^{1/2}|\log \epsilon|^{-7/2}, \epsilon^{-1}|\log \epsilon|^{-3}\sqrt{\alpha(|\log \epsilon|^{-3})/2}\}. \quad (2.65)$$

Since $\mathcal{G}\bar{q} \geq \mathcal{G}\underline{\varrho}$ we are done. \square

From the comparison theorem (Proposition 3.1), we can construct a probability space on which the solution of

$$\begin{cases} \partial_t \underline{u} = \partial_x^2 \underline{u} + \underline{f}(\underline{u}) + \epsilon \sigma(\underline{u}) \dot{W}, & |x| < L + vt \\ \underline{u}(t, x) = 0, & |x| \geq L + vt. \end{cases} \quad (2.66)$$

gives an almost sure lower bound for the solution of (1.1) with the same initial data.

Suppose we start (2.66) with $\underline{\varrho}_0(x)$ from Lemma 2.5. The idea is that the solution \underline{u} will stay close to $\underline{\varrho}$ up to time 1. To see how close, let us make a very rough argument. Since \underline{f} has Lipschitz constant 1 one expects that for times of $\mathcal{O}(1)$, $|\underline{u}(t, x) - \underline{\varrho}(t, x)|$ is controlled by something like $\epsilon|Z_{L,v}(t, x)|$ where

$$Z_{L,v}(t, x) = \int_0^t \int_0^s e^{t-s} G_{v,L}(s, y, t, x) \sigma(u(s, y)) W(ds dy). \quad (2.67)$$

The actual bound is somewhat more complicated, but it amounts to the same thing. Recall that $\sigma^2(u) \leq u$. By concavity of \underline{f} , $E[u] \leq \underline{\varrho}$. So

$$E[Z_{L,v}^2(1, x)] \leq \epsilon \mathcal{G}\underline{\varrho}(1, x). \quad (2.68)$$

Things are tight in the region close to the front $\{x = vt + L\}$ where $\underline{\varrho} = \mathcal{O}(\varepsilon^2)$. Here $\mathcal{G}\underline{\varrho}(1, x) = \mathcal{O}(\varepsilon^2)$ as well. Hence the fluctuations of $\underline{u} - \underline{\varrho}$ are of order $\epsilon\varepsilon = \gamma\varepsilon^2$ there. This is the reasoning behind (2.59). The key point of the following refined large deviation estimate is that it shows that the fluctuations near the front are of $\mathcal{O}(\gamma\varepsilon^2)$ instead of the $\mathcal{O}(\epsilon)$ one would obtain naively.

Lemma 2.6. *Let $\underline{\varrho}$, L be as in Lemma 2.5. There exists $C_{(2.69)} < \infty$ such that for all $0 < r < \epsilon^{-1}$,*

$$P\left(\exists x : \underline{u}(1, x) \leq \underline{\varrho}(1, x) - r\epsilon\sqrt{\mathcal{G}\underline{\varrho}(1, x)}\right) \leq 4L \exp\{-C_{(2.69)}^{-1}r^2\}. \quad (2.69)$$

Note the factor L on the right hand side is because the large deviations are done on space intervals of size 1, and then summed over the width of $\underline{\varrho}(1, x)$. If we take

$$r^2 = C_{(2.69)}[|\log \epsilon|^3 + 2\log|\log \epsilon| + \log 4], \quad (2.70)$$

the right hand side is less than $|\log \epsilon|^{-1}e^{-|\log \epsilon|^3}$. We conclude that if we start (2.66) with $\underline{\varrho}_0(x)$, then

$$P(u(1, x) \geq \underline{\varrho}_0(x - v), \quad x \in \mathbf{R}) \geq 1 - |\log \epsilon|^{-1}e^{-|\log \epsilon|^3}. \quad (2.71)$$

Now we can ask for this to happen $T = |\log \epsilon|$ times, to obtain

$$P(u(T, x) \geq \underline{\varrho}_0(x - vT), \quad x \in \mathbf{R}) \geq 1 - e^{-|\log \epsilon|^3} \stackrel{\text{def}}{=} p. \quad (2.72)$$

By symmetry we also have

$$P(u(T, x) \geq \underline{\varrho}_0(x + vT), \quad x \in \mathbf{R}) \geq p. \quad (2.73)$$

This allows us to compare the system to a 2-dependent oriented percolation. Let $\mathcal{L} = \{(m, n) \in \mathbf{Z}^2 : m + n \text{ is even}, m \geq 0\}$. Let $\hat{\mathcal{L}}$ denote the set of directed bonds $(m, n) \rightarrow (m + 1, n + 1)$ or $(m, n) \rightarrow (m + 1, n - 1)$. Let X_b , $b \in \hat{\mathcal{L}}$ be random variables taking values in $\{0, 1\}$. Assume that for all $b \in \hat{\mathcal{L}}$,

$$P(X_b = 1) \geq p. \quad (2.74)$$

Also assume that X_b and $X_{b'}$ are independent if the lattice distance between b and b' is strictly larger than 2. If $m_1 < m_2$ then we say $(m_1, n_1) \rightarrow (m_2, n_2)$ if they are joined by a sequence of directed bonds $b_i \in \hat{\mathcal{L}}$ with $X_{b_i} = 1$. Let \mathcal{S} denote the subset of $(m, n) \in \mathcal{L}$ such that $(0, x) \rightarrow (m, n)$ for some $x < 0$.

Lemma 2.7. *Suppose that*

$$p > 1 - e^{-10}. \quad (2.75)$$

Then, with probability 1, for all but finitely many m ,

$$N_m \stackrel{\text{def}}{=} \max\{n : (m, n) \in \mathcal{S}\} \geq (1 - 10|\log(1 - p)|^{-1})m \quad (2.76)$$

Proof. Using the standard contour counting argument one obtains

$$P(N_m < m(1 - \delta)) \leq \sum_{n \geq m\delta} 4^{2n+m}(1 - p)^{n/2}. \quad (2.77)$$

(see [CD04], Lemma 3.6, for a complete proof of (2.77). The only difference is the exponent $n/2$ on the $(1 - p)$ which comes from the 2-dependence.) Take $\delta = 10|\log(1 - p)|^{-1}$. If we assume (2.75) then it is not hard to check that the right hand side is less than $2e^{-M}$ and the result follows from Borel-Cantelli. \square

Remark. (2.76) is very far from optimal: It is known (see [D], [GP]) that for p close to 1, the speed of oriented percolation, $\lim_{m \rightarrow \infty} \frac{N_m}{m} = 1 - \mathcal{O}(1-p)$. If one uses the stronger result, one can check for the case (1.9), (1.10), the main result holds with $\epsilon_0 = e^{-11}$.

Proof of the lower bound. Start (1.1) with initial data u_0 in \mathcal{C}_{exp} satisfying (1.6). Without loss of generality, $x_0 = 0$. As long as $\theta > \alpha$ we have $u_0(x) \geq \sum_{n=-\infty}^0 \underline{\rho}_0(x - nT)$. We say $X_{(m,n) \rightarrow (m+1,n \pm 1)} = 1$ if $u(mT, x + nT), u((m+1)T, x + (n \pm 1)T) \geq \underline{\rho}_0(x)$. Recall $r(t) = \sup\{x \in \mathbf{R} : u(t, x) > 0\}$. If $N_m \geq am$, then $r(mT) \geq amT$, and furthermore, $r(t) \geq (am-1)t - L$, $(m-1)T \leq t \leq mT$. Hence from Lemma 2.7 we get a lower bound

$$\underline{v}_\epsilon \geq v(\epsilon^2) - 10|\log(1-p)|^{-1} = v(\epsilon^2) - 10|\log \epsilon|^{-3}. \quad (2.78)$$

3 Comparison

We now state precisely the comparison theorem we are using. Let U denote the set

$$U = \{(t, x) \in [0, T] \times \mathbf{R} : x \leq vt\} \quad (3.1)$$

for some $v > 0$

Proposition 3.1. *Assume (1.7), (1.8).*

1. *Suppose that $g(t, u) \leq f(u)$ are Lipschitz functions, $u \in \mathbf{R}$, $t \geq 0$ and initial data $v_0(x) \leq u_0(x)$, $x \in \mathbf{R}$ are given. There exists a probability space (Ω, \mathcal{F}, P) on which there are white noises \dot{W}, \dot{W}_1 , a solution u to (1.1); a solution v to*

$$\begin{cases} \partial_t v = \partial_x^2 v + g(v) + \epsilon \sigma(v) \dot{W}_1, & (t, x) \in U, \\ v(t, x) = 0, & (t, x) \notin U, \end{cases} \quad (3.2)$$

with $v(0, x) = v_0(x)$, and satisfying

$$u(t, x) \geq v(t, x), \quad x \in \mathbf{R}, \quad t > 0. \quad (3.3)$$

2. *Fix possibly random \mathcal{F}_0 -measurable $u_0 \in \hat{\mathcal{C}}$. Suppose that $g(u)$ is the Lipschitz function and there is also another initial data $\bar{u}_0 = v_0 \in \mathcal{C}_{\text{exp}}$ such that*

$$u_0(\cdot) \leq \bar{u}_0(\cdot), \quad \text{a.s.},$$

and $\bar{u}_0(x) = 0$ for all $x \geq 0$. Then there exists a probability space (Ω, \mathcal{F}, P) on which white noises $\dot{W}, \dot{\bar{W}}, \dot{W}_1, \dot{W}_2$ and a vector of processes (u, \bar{u}, v, \bar{v}) are defined and satisfy the following properties:

- (i) *u is a solution to (1.1);*
- (ii) *\bar{u} is a solution to (1.1) in \mathcal{C}_{exp} starting at \bar{u}_0 with \bar{W} replacing W ;*
- (iii) *v is a solution to (3.2) in \mathcal{C}_{exp} starting at $v_0 = \bar{u}_0$ where U is of the form (3.1);*
- (iv) *\dot{W}_2 is a space-time white noise independent of \dot{W}_1 ;*

(v) Up to time

$$\tau = \inf\{t \geq 0 : \exists x, \sigma_w^2(t, x) =: \sigma^2(\bar{u}) - \sigma^2(v) = 0, \bar{u}(t, x) \neq v(t, x)\}, \quad (3.4)$$

$$\bar{u} - v \leq \bar{w} \quad \text{and} \quad u \leq \bar{u} \quad \text{a.s.}, \quad (3.5)$$

where

$$\partial_t \bar{w} = \partial_x^2 \bar{w} + \bar{w} + \epsilon \sigma_w \dot{W}_2 + \delta_{x-v_{\text{com}} t} \dot{A}, \quad (3.6)$$

and

$$A(t) = - \int (v(t, x) - v(0, x)) dx + \int \int_0^t g(v(s, x)) ds dx + \epsilon \int \int_0^t \sigma(v(s, x)) W_1(ds dx).$$

Proof. 1. Assume first that σ is globally Lipschitz. Then the proof goes essentially along the lines of Theorem 3.1 of [MP92]. One approximates the solutions by lattice versions as in (1.15), for which the ordering is elementary. Then one shows the ordering is preserved in the limit. Because one has strong uniqueness it means the solution of the SPDE's are ordered in the desired way. Now suppose we do not have the strong uniqueness. We construct a sequence of Lipschitz $\sigma^{(n)}$ converging uniformly to σ and consider the sequence of solutions $u^{(n)}, v^{(n)}$ corresponding to $\sigma^{(n)}$. It is a standard to check that the sequence is tight and any weak limit point satisfies our equations. Since comparison is satisfied for each n it also holds in the limit.

2. There exists a probability space with a noise \dot{W} and a pair of independent noises \dot{W}_1 and \dot{W}_2 such that u solves (1.1), v solves (3.2) and \tilde{w} solves

$$\partial_t \tilde{w} = \partial_x^2 \tilde{w} + f(\tilde{w} + v) - f(v) + \tilde{\sigma}_w \dot{W}_2 + \delta_{x-\kappa t} \dot{A}, \quad (3.7)$$

where $\tilde{\sigma}_w^2 = |\sigma^2(v + \tilde{w}) - \sigma^2(v)|$, \tilde{w} is non-negative and

$$u \leq v + \tilde{w}. \quad (3.8)$$

The construction of such a tripple (u, v, \tilde{w}) is fairly straightforward. One constructs a sequence of approximations to (1.1), (3.2) and (3.7) for which the ordering correspondent to (3.8) is elementary. Then one takes a limit to get solutions to (1.1), (3.2) and (3.7) and shows that ordering is preserved in the limit. By this way one gets that the the unique weak solution u to (1.1) is bounded from the above by $v + \tilde{w}$ where v, \tilde{w} are *some* solutions to (3.2) and (3.7) respectively with independent white noises \dot{W}_1, \dot{W}_2 .

Define

$$\tilde{u} = v + \tilde{w}, \quad t \leq \tau_1 \quad (3.9)$$

$$\partial_t \tilde{u} = \partial_x^2 \tilde{u} + f(\tilde{u}) + \epsilon \sigma(\tilde{u}) \dot{W}, \quad t \geq \tau_1, \quad (3.10)$$

where τ_1 is defined similarly to τ :

$$\tau_1 = \inf\{t \geq 0 : \exists x, \tilde{\sigma}_w^2(t, x) = 0, (v + \tilde{w})(t, x) \neq v(t, x)\}.$$

It is easy to see that \tilde{u} is a solution to the equation which \bar{u} is supposed to solve, and hence we can set $\bar{u} = \tilde{u}$ and $\tau_1 = \tau$. To show that \bar{u} and v indeed belong to \mathcal{C}_{exp} one can use for example the methods of proof of Theorem 1.2 from [MPS06]. Now let us construct \bar{w} satisfying (3.6) such that

$$\tilde{w} \leq \bar{w}, \text{ on } t \leq \tau.$$

Let w be a solution to

$$\partial_t w = \partial_x^2 w + (w + \tilde{w}) - (f(\tilde{w} + v) - f(v)), \quad t \leq \tau. \quad (3.11)$$

As the drift term is non-negative we get that w is non-negative. Now define $\bar{w} = w + \tilde{w}$ and it is easy to check that it satisfies (3.6) and we are done. \square

4 Large deviations

We now present a fairly standard type of large deviation result which covers the estimates we need both in the upper and lower bounds. We need some notation. Let $g(s, y, t, x)$ and $\eta(x, y)$ be deterministic, and

$$\Gamma_{b,T} = \{(t, x) : t \in [0, T], x - vt \in [b - 1, b]\}. \quad (4.1)$$

For (t, x) and (t', x') in $\Gamma_{b,T}$ let

$$d((t, x), (t', x')) = |x' - x| + |t' - t|^{1/2}. \quad (4.2)$$

Define

$$\mathcal{B}(g, \eta, b) = \sup_{\substack{(t,x),(t',x') \in \Gamma_{b,T} \\ d((t,x),(t',x')) \leq 1}} \frac{\int \int_0^\infty [g(s, y, t', x') - g(s, y, t, x)]^2 \eta(s, y) ds dy}{d((t, x), (t', x'))}. \quad (4.3)$$

Lemma 4.1. *Let $g(s, y, t, x)$, $\eta(s, y)$, $\Gamma_{b,T}$ and $\mathcal{B}(g, \eta, b)$ be as above and $\sigma(t, x)$ nonanticipating with*

$$|\sigma(t, x)|^2 \leq \eta(t, x), \quad (t, x) \in [0, T] \times \mathbf{R} \quad (4.4)$$

almost surely, and define

$$Z(t, x) = \int \int_0^t g(s, y, t, x) \sigma(s, y) W(ds dy). \quad (4.5)$$

There exist $C_{(4.6)}, C_{(4.7)} < \infty$ such that if $T \geq 1$ and

$$\ell \geq C_{(4.6)} T B^{1/2} \quad (4.6)$$

Then, with $\Phi(d) = \sqrt{d(1 + |\log_2 d|)}$,

$$P \left(\sup_{(t,x),(t',x') \in \Gamma_{b,T}} \frac{|Z(t', x') - Z(t, x)|}{\Phi(d((t, x), (t', x')))} \geq \ell \right) \leq 4T \exp \left\{ -C_{(4.7)}^{-1} \ell^2 T^{-2} B^{-1} \right\}. \quad (4.7)$$

Proof. Let \mathcal{G}_n be the vertices of an affine lattice with edges \mathcal{E}_n parallel to the boundaries of $\Gamma_{b,T}$ and with edge lengths 2^{-n} in the $(1, 0)$ direction and with vertical component 2^{-2n} in the $(1, v)$ direction. Let $\mathcal{G} = \cup_{n=0}^{\infty} \mathcal{G}_n$ and $\mathcal{E} = \cup_{n=0}^{\infty} \mathcal{E}_n$.

Given $(t, x), (t', x') \in \mathcal{G}$ with

$$\min(d((t, x), (t', x')), 1) \in (2^{-n_0}, 2^{-(n_0-1)}] \quad (4.8)$$

there exists a path between them using edges from \mathcal{E} , which uses only edges from \mathcal{E}_n with $n \geq n_0$, and uses at most T edges from any given \mathcal{E}_n .

For $e = (p, q) \in \mathcal{E}_n$, write $Z_e := Z(p) - Z(q)$ and $d_e = d(p, q)$. By standard Itô calculus,

$$E[\exp\{\gamma Z_e\}] \leq \exp\{\frac{1}{2}\gamma^2 d_e \mathcal{B}\}. \quad (4.9)$$

Let $a_n = (10\sqrt{2}T)^{-1}(n+1)^{1/2}2^{-n/2}$ and

$$\mathcal{A}_e = \{Z_e \leq a_n \ell\}. \quad (4.10)$$

By Chebyshev's inequality

$$P(\mathcal{A}_e^c) \leq \exp\{\frac{1}{2}\gamma^2 d_e \mathcal{B} - \gamma a_n \ell\}. \quad (4.11)$$

Optimising the inequality over γ gives

$$P(\mathcal{A}_e^c) \leq \exp\{-\frac{1}{2}\ell^2 a_n^2 d_e^{-1} \mathcal{B}^{-1}\}. \quad (4.12)$$

Let $\mathcal{A} = \bigcap_{n=0}^{\infty} \bigcap_{e \in \mathcal{E}_n} \mathcal{A}_e$. On \mathcal{A} ,

$$|Z(t', x') - Z(t, x)| \leq T\ell \sum_{n=n_0}^{\infty} a_n \quad (4.13)$$

$$\leq \ell(n_0 + 1)^{1/2} 2^{-n_0/2} \quad (4.14)$$

$$\leq \ell \Phi(d((t, x), (t', x'))). \quad (4.15)$$

Here we use the fact that for $n_0 \geq 0$, $\sum_{n=n_0+1}^{\infty} n^{1/2} 2^{-n/2} \leq 10(n_0 + 1)^{1/2} 2^{-n_0/2}$. Now we have

$$P(\mathcal{A}^c) \leq \sum_{n=0}^{\infty} \sum_{e \in \mathcal{E}_n} P(\mathcal{A}_e^c) \leq \sum_{n=0}^{\infty} |\mathcal{E}_n| P(\mathcal{A}_e^c). \quad (4.16)$$

It is simple to check that $|\mathcal{E}_n| \leq 2T2^{3n}$ and $d_e \leq 2^{-n+2}$. From (4.12) then,

$$P(\mathcal{A}^c) \leq 2Te^{-2^{-10}\ell^2 T^{-2} \mathcal{B}^{-1}} (1 - e^{3 \log 2 - 2^{-10}\ell^2 T^{-2} \mathcal{B}^{-1}}) \quad (4.17)$$

which gives (4.7) as long as (4.6) holds. Since $Z(s, y)$ is continuous, it is enough to check the bound on dyadics, and hence this completes the proof. \square

In order to apply Lemma we need a bound on (4.3). This is provided by the next lemma. The lemma will only be applied with the λ defined in (2.14), but it is true for other λ satisfying (4.20).

Lemma 4.2. *Let*

$$g(s, y, t, x) = e^{a(t-s)} 1(0 \leq s \leq t) G_v(s, y, t, x) \quad (4.18)$$

and

$$\eta(s, y) \leq (1 + |y - vs|) \exp\{\lambda|y - vs|\}. \quad (4.19)$$

Then, there exists $C_{(4.21)} < \infty$ such that for any $b < 0$ (i) if $T \leq 1$ and $a \leq 1$, or (ii) if $T > 1$ and

$$v\lambda - \frac{\lambda^2}{2} \geq 2a, \quad (4.20)$$

\mathcal{B} from (4.3) satisfies

$$\mathcal{B} \leq C_{(4.21)}(1 + |b|)e^{\lambda|b|}. \quad (4.21)$$

The same also holds in case (i) if G_v is replaced by $G_{v,L}$.

Proof. The only statement that is not elementary is (ii). We have to estimate

$$\begin{aligned} & \int_0^\infty \int_0^\infty [g(s, y, t+h, x+z) - g(s, y, t, x)]^2 (1 + |y - vs|) \exp\{\lambda|y - vs|\} ds dy \\ & \leq C(1 + |b|)e^{\lambda|b|}[z + h^{1/2}] \end{aligned} \quad (4.22)$$

for $t \in [0, T]$, $x - vt \in [b-1, b]$, with $g(s, y, t, x)$ in (4.18). First of all, note that we can express G_v in terms of G_0 , which in turn can be written explicitly in terms of the heat kernel G (see (1.13)) using reflection;

$$G_v(s, y, t, x) = e^{-\frac{v}{2}((x-vt)-(y-vs)) - \frac{v^2}{4}(t-s)} G_0(s, y - vs, t, x - vt), \quad (4.23)$$

$$G_0(s, y, t, x) = G(s, y, t, x) - G(s, y, t, -x), \quad x, y < 0. \quad (4.24)$$

After change of variables, the left hand side of (4.22) becomes, with $x' = x - vt$ and $\gamma = z - vh$,

$$\begin{aligned} & \int_{y \leq 0} \int \left(\mathbf{1}_{0 \leq s \leq t+h} e^{-\frac{v}{2}(x'-y+\gamma) - \alpha(t-s+h)} G_0(s, y, t+h, x' + \gamma) \right. \\ & \quad \left. - \mathbf{1}_{0 \leq s \leq t} e^{-\frac{v}{2}(x'-y) - \alpha(t-s)} G_0(s, y, t, x') \right)^2 (1 + |y|) e^{\lambda|y|} ds dy. \end{aligned} \quad (4.25)$$

with $\alpha = \frac{v^2}{4} - a$. Estimating the two pieces of the right hand side of (4.24) by using that the square of the sum is bounded by twice the sum of the squares we see that (4.25) is bounded by the sum over $\iota = \pm 1$ of

$$\begin{aligned} & \int_{y \leq 0} \int \left(\mathbf{1}_{-h \leq s \leq t} \frac{\exp\{-\frac{v}{2}(x' - y + \gamma) - \alpha(s+h) - \frac{(x' - \iota y + \gamma)^2}{4(s+h)}\}}{\sqrt{s+h}} \right. \\ & \quad \left. - \mathbf{1}_{0 \leq s \leq t} \frac{\exp\{-\frac{v}{2}(x' - y) - \alpha s - \frac{(x' - \iota y)^2}{4s}\}}{\sqrt{s}} \right)^2 (1 + |y|) e^{-\lambda y} \frac{ds dy}{4\pi} \end{aligned} \quad (4.26)$$

Note that we have also changed variables $t - s \mapsto s$. Changing $y \mapsto y + x'$ and rearranging a little this becomes $(A_1 + A_0|x'|)e^{-\lambda x'}$ where A_i is $(4\pi)^{-1}$ times the sum over $\iota = \pm 1$ of

$$\iint e^{-2\alpha s + (\nu - \lambda)y} (1 + \iota|y|) \left(\mathbf{1}_{-h \leq s \leq t} \frac{\gamma' e^{-\frac{(y + (1-\iota)x - \iota\gamma)^2}{4(s+h)}}}{\sqrt{s+h}} - \mathbf{1}_{0 \leq s \leq t} \frac{e^{-\frac{(y + (1-\iota)x)^2}{4s}}}{\sqrt{s}} \right)^2 ds dy \quad (4.27)$$

with $\gamma' = \exp\{\frac{\nu\gamma}{2} - \alpha h\}$. Consider the $\iota = +1$ term. We estimate

$$\begin{aligned} & \left(\mathbf{1}_{-h \leq s \leq t} \frac{\gamma' e^{-\frac{(y-\gamma)^2}{4(s+h)}}}{\sqrt{s+h}} - \mathbf{1}_{0 \leq s \leq t} \frac{e^{-\frac{y^2}{4s}}}{\sqrt{s}} \right)^2 \leq 3 \cdot \mathbf{1}_{0 \leq s \leq t} \left(\frac{e^{-\frac{(y-\gamma)^2}{4(s+h)}}}{\sqrt{s+h}} - \frac{e^{-\frac{y^2}{4s}}}{\sqrt{s}} \right)^2 \\ & + 3 \cdot \mathbf{1}_{-h \leq s \leq 0} \frac{\gamma'^2 e^{-\frac{(y-\gamma)^2}{2(s+h)}}}{s+h} + 3 \cdot \mathbf{1}_{0 \leq s \leq t} \frac{(\gamma' - 1)^2 e^{-\frac{(y-\gamma)^2}{2(s+h)}}}{s+h}. \end{aligned} \quad (4.28)$$

There are also three analogous terms corresponding to $\iota = -1$. All six terms are estimated by explicit computation. Since it is very tedious, we present only the worst case which is the first term on the right hand side of (4.28) with $\iota = 1$. Call $\beta = \nu - \lambda$.

Lemma 4.3. *For $h, \gamma \in (0, 1)$, $\alpha, \beta \in (0, 3)$ and*

$$q = 2\alpha - \beta^2 > 0, \quad (4.29)$$

there exists a $C_{(4.30)} < \infty$ such that for all $t > 0$,

$$\int_0^t \int e^{-2\alpha s + \beta y} (1 + |y|) \left(\frac{e^{-\frac{(y-\gamma)^2}{4(s+h)}}}{\sqrt{s+h}} - \frac{e^{-\frac{y^2}{4s}}}{\sqrt{s}} \right)^2 dy ds \leq C_{(4.30)}[|\gamma| + |h|^{1/2}] \quad (4.30)$$

Proof. The left hand side is bounded by a constant multiple of $\mathbb{I}_1 + \mathbb{I}_2 + \mathbb{I}_3(\gamma^2 - h) + \mathbb{I}_4(h) + \mathbb{I}_4$ where

$$\begin{aligned} \mathbb{I}_1 &= \int_h^t \int e^{-2\alpha s + \beta y} (1 + |y|) \left(\frac{e^{-\frac{y^2}{4(s+h)}}}{\sqrt{s}} - \frac{e^{-\frac{y^2}{4s}}}{\sqrt{s+h}} \right)^2 dy ds \\ \mathbb{I}_2 &= \int_h^t \int e^{-2\alpha s + \beta y} (1 + |y|) \left(\frac{e^{-\frac{y^2}{4(s+h)}}}{\sqrt{s+h}} - \frac{e^{-\frac{y^2}{4s}}}{\sqrt{s}} \right)^2 dy ds \\ \mathbb{I}_3(a) &= \int_0^{|a|} \int e^{-2\alpha s + \beta y} (1 + |y|) \left(\frac{e^{-\frac{y^2}{2(s+h)}}}{s+h} + \frac{e^{-\frac{(y-\gamma)^2}{2s}}}{s} \right) dy ds \\ \mathbb{I}_4 &= \int_{0 \vee (\gamma^2 - h)}^t \int e^{-2\alpha s + \beta y} \frac{(1 + |y|)}{s+h} \left(e^{-\frac{(y-\gamma)^2}{4(s+h)}} - e^{-\frac{y^2}{4(s+h)}} \right)^2 dy ds \end{aligned}$$

In the proof C will denote any finite constant, possibly depending on α, β and q . Its value will change from line to line.

Estimation of $\mathbb{I}_1 \leq Ch^{1/2}$. By the mean value theorem, there exists $\theta \in [0, 1]$ such that

$$\mathbb{I}_1 = \frac{1}{16} h^2 \int_h^t \int e^{-2\alpha s + \beta y} (1 + |y|) s^{-1} e^{-\frac{y^2}{2(s+\theta h)}} y^4 (s + \theta h)^{-4} dy ds. \quad (4.31)$$

Since we are integrating over $s \in [h, t]$, we have $s \leq s + \theta h \leq 2s$ and therefore

$$\begin{aligned} \mathbb{I}_1 &\leq Ch^2 \int_h^t \int e^{-2\alpha s + \beta y} e^{-\frac{y^2}{4s}} (y^4 + |y|^5) s^{-5} dy ds \\ &= Ch^2 \int_h^t e^{-qs} s^{-5} \int e^{-\frac{1}{4s}(y-2s\beta)^2} (y^4 + |y|^5) dy ds. \end{aligned}$$

Recall that $|a + b|^n \leq 2^{n-1}(|a|^n + |b|^n)$. Thus $y^4 = ((2s)^{\frac{1}{2}}z + 2s\beta)^4 \leq 2^5 z^4 s^2 + 2^7 s^4 \beta^4$, $|y|^5 = |(2s)^{\frac{1}{2}}z + 2s\beta|^5 \leq 2^{\frac{43}{2}} z^5 s^{\frac{5}{2}} + 2^9 s^5 \beta^5$. After the change of variables change variables to $z = (y - 2s\beta)/\sqrt{2s}$ and integrating we can bound the last term by

$$Ch^2 \int_h^t e^{-qs} \left(s^{-\frac{5}{2}} + s^{-2} + s^{-\frac{1}{2}} \beta^4 + s^{\frac{1}{2}} \beta^5 \right) ds \quad (4.32)$$

where C is a universal constant. Since $s > h$ in the region of integration and $h \leq 1$, this is bounded above by

$$Ch^2 \int_h^t e^{-qs} \left(h^{-\frac{1}{2}} s^{-2} + s^{-2} + h^{-\frac{1}{2}} \beta^4 + h^{\frac{1}{2}} \beta^5 \right) ds \quad (4.33)$$

The estimate then follows from $\int_h^t e^{-qs} s^{-2} ds \leq \int_h^1 s^{-2} ds + \int_1^t e^{-qs} ds \leq \frac{1}{h} + q^{-1}$.

Estimation of $\mathbb{I}_2 \leq Ch^{\frac{1}{2}}$. By the mean value theorem, there exists $\theta \in [0, 1]$ such that

$$\begin{aligned} \mathbb{I}_2 &= \frac{1}{4} h^2 \int_h^t \int e^{-2\alpha s + \beta y} (1 + |y|) e^{-\frac{y^2}{2(s+\theta h)}} (s + \theta h)^{-3} dy ds \\ &\leq Ch^2 \int_h^t \int e^{-2\alpha s + \beta y} (1 + |y|) e^{-\frac{y^2}{2(2s)}} s^{-3} dy ds \\ &= Ch^2 \int_h^t e^{-qs} s^{-\frac{5}{2}} (\pi^{\frac{1}{2}} + 2s^{\frac{1}{2}} + 2\pi^{\frac{1}{2}} s \beta) ds \end{aligned}$$

The estimate then follows from $\int_h^t e^{-qs} s^{-\frac{5}{2}} (1 + s^{\frac{1}{2}} + s) ds \leq \int_h^\infty \left(s^{-\frac{5}{2}} + s^{-2} + s^{-\frac{3}{2}} \right) ds \leq Ch^{-\frac{3}{2}}$.

Estimation of $\mathbb{I}_3(\gamma^2 - h) + \mathbb{I}_3(h) \leq C[h^{\frac{1}{2}} + \gamma]$. This just uses $\int (1 + |y|) e^{-\frac{(y-a)^2}{2r}} dy \leq \int (1 + a + |y - a|) e^{-\frac{(y-a)^2}{2r}} dy \leq C((1 + a)r^{\frac{1}{2}} + r)$ and $4\alpha - \beta^2 > 0$.

Estimation of $\mathbb{I}_4 \leq C\gamma$. First we change variables to $r = s + h$, with h constant, and use the fact that $2\alpha r \geq 0$ and $t < \infty$ to see that

$$\mathbb{I}_4 \leq e^{2\alpha h} \int_{h \vee \gamma^2}^\infty \int I(r, y) dy dr \quad (4.34)$$

where

$$\begin{aligned}
I(r, y) &= r^{-1}(1 + |y|) \left(e^{-\frac{(y-\gamma-\beta r)^2}{4r}} e^{\frac{\gamma\beta}{2}} e^{\frac{\beta^2 r}{4}} - e^{-\frac{(y-\beta r)^2}{4r}} e^{\frac{\beta^2 r}{4}} \right)^2 \\
&\leq 2e^{-(2\alpha + \frac{\beta^2}{2})r} r^{-1}(1 + |y|) e^{-\frac{(y-\gamma-\beta r)^2}{2r}} \left(e^{\frac{\gamma\beta}{2}} - 1 \right)^2 \\
&\quad + 2e^{-(2\alpha + \frac{\beta^2}{2})r} r^{-1}(1 + |y|) \left(e^{-\frac{(y-\gamma-\beta r)^2}{4r}} - e^{-\frac{(y-\beta r)^2}{4r}} \right)^2 \\
&=: I_1(r, y) + I_2(r, y)
\end{aligned} \tag{4.35}$$

We have $(e^{\frac{\gamma\beta}{2}} - 1)^2 \leq C\gamma^2$ and furthermore $\int (1 + |y|) e^{-\frac{(y-\gamma-\beta r)^2}{2r}} dy \leq \int (1 + \gamma + \beta r + |y - \gamma - \beta r|) e^{-\frac{(y-\gamma-\beta r)^2}{2r}} dy \leq C[r^{1/2}(1 + \gamma + \beta r) + r]$ so,

$$\int_0^\infty \int I_1(r, y) dy dr \leq C\gamma^2. \tag{4.36}$$

Similarly we bound $\int I_2(r, y) dy$ by

$$2 \int e^{-(2\alpha + \frac{\beta^2}{2})r} r^{-1} (1 + \beta r + \frac{\gamma}{2} + |y - \beta r - \frac{\gamma}{2}|) (e^{-\frac{(y-\gamma-\beta r)^2}{4r}} - e^{-\frac{(y-\beta r)^2}{4r}})^2 dy. \tag{4.37}$$

We need two standard estimates: For $r > 0$,

$$\int (e^{-\frac{(y-\gamma)^2}{4r}} - e^{-\frac{y^2}{4r}})^2 dy \leq Cr^{-\frac{1}{2}}\gamma^2 \tag{4.38}$$

$$\int |y - \frac{\gamma}{2}| (e^{-\frac{(y-\gamma)^2}{4r}} - e^{-\frac{y^2}{4r}})^2 dy \leq C(r^{\frac{1}{2}}\gamma + \gamma^2) \tag{4.39}$$

Changing variables in (4.37) to $z = y - \beta r$ and using (4.38), (4.39) we have

$$\int_{\gamma^2}^\infty \int I_2(r, y) dy dr \leq C\gamma \tag{4.40}$$

which gives the required estimate for \mathbb{I}_4 and completes the proof of the lemma. \square

This gives us a lemma which controls the large deviations on a long time interval.

Lemma 4.4. *Let*

$$Z(t, x) = \int_0^t \int_0^t e^{-(t-s)} G_v(s, y, t, x) \sigma(s, y) W(ds dy) \tag{4.41}$$

where σ is nonanticipating. Assume

$$\sigma^2(t, x) \leq \bar{F}(x - vt) + 3e^{-\lambda(x-vt)}. \tag{4.42}$$

Then for T be as in (2.50),

$$P(\exists(t, x) \in [0, T] \times \mathbf{R}, x \leq vt : Z(t, x) \geq \epsilon^{-1} e^{-\lambda(x-vt)}) \leq 1/16 \quad (4.43)$$

and with M as in (2.45),

$$P\left(\sup_{0 \leq t \leq T, vt-M \leq x \leq vt} |Z(t, x)| \geq \epsilon^{-1} u^*/160\right) \leq 1/32 \quad (4.44)$$

Proof. The left hand side of (4.43) is bounded by

$$\sum_{n=0}^{\infty} P(\exists(t, x) \in \Gamma_{-n, T} : Z(t, x) \geq \epsilon^{-1} e^{\lambda n}) \quad (4.45)$$

where $\Gamma_{-n, T}$ is defined in (4.1). Applying Lemma 4.1 for each n with

$$\ell = \epsilon^{-1} e^{\lambda n} / 2\sqrt{T \log T} \quad (4.46)$$

using $t' = 0$ and $\Phi \leq 2\sqrt{T \log T}$ and (4.21), we obtain that (4.45) is bounded by

$$4|\log \epsilon|^4 \sum_{n=0}^{\infty} \exp\{-A(n+1)^{-1} e^{\lambda n}\} \quad (4.47)$$

with $A = \epsilon^{-2} C_{(4.47)}^{-1} |\log \epsilon|^{-12} |\log \log \epsilon^{-1}|^{-1}$ as long as

$$\ell = \epsilon^{-1} e^{\lambda n} / 2\sqrt{T \log T} \geq C_{(4.6)} T \mathcal{B}^{1/2} \quad (4.48)$$

From (2.14), $\lambda - 1 \geq 1$ if $\delta > 0.2$. Hence $(n+1)^{-1} e^{\lambda n} \geq n+1$ for all $n \geq 0$ and (4.47) is bounded above by

$$4|\log \epsilon|^4 \sum_{n=0}^{\infty} \exp\{-A(n+1)\} \leq 8|\log \epsilon|^4 e^{-A} \quad (4.49)$$

as long as $A \geq \log 2$ which bounded by $1/16$ for $\epsilon \leq \epsilon_0$. \square

5 Proof of Lemma 2.2

Recall that v and ϱ are the solution of (2.31) and (2.1) with initial data \bar{F} as in (2.24). γ, L, T, M are as in (2.47), (2.48), (2.29).

Lemma 2.2 is basically a result about how the stochastic perturbation of a partial differential equation (2.31) stays close to its deterministic version. Such theorems are fairly standard, but we need to stay close on a fairly long time interval $[0, T]$ where $T = \mathcal{O}(|\log \epsilon|^4)$ as required by (2.46). First of all, let \bar{v} be the solution of

$$\begin{cases} \partial_t \bar{v} = \partial_x^2 \bar{v} + \bar{f}(\bar{v}) + \epsilon \sigma(\bar{v}) \dot{W}_1, & x < vt, \\ \bar{v}(t, x) = 0, & x \geq vt, \end{cases} \quad (5.1)$$

with $\bar{v}(0, x) = \bar{F}(x)$ with $\bar{v} \geq v$ by the comparison theorem, and let $\bar{\varrho}$ be the solution of (2.21). It suffices to show that

$$P\left(\exists t \in [0, T] : \bar{v}(t, x) > \bar{\varrho}(t, x) + 3\lambda e^{-\lambda(x-vt)} \text{ for some } x \in \mathbb{R}\right) \leq 1/16. \quad (5.2)$$

We have

$$\partial_t(\bar{v} - \bar{\varrho}) = \partial_x^2(\bar{v} - \bar{\varrho}) + \bar{f}(\bar{v}) - \bar{f}(\bar{\varrho}) + \epsilon\sigma(\bar{v})\dot{W}_1 \quad x < vt \quad (5.3)$$

and $\bar{v} - \bar{\varrho} = 0$ on $x \geq vt$ and $t = 0$. One easily checks that

$$\bar{f}(\bar{v}) - \bar{f}(\bar{\varrho}) \leq 2 - (\bar{v} - \bar{\varrho}). \quad (5.4)$$

Using the same ideas as in the proof of Proposition 3.1 we will show now that

$$\bar{v} - \bar{\varrho} \leq y \quad (5.5)$$

with y a solution of

$$\partial_t y = \partial_x^2 y + 2 - y + \epsilon\sigma(v)\dot{W}_1. \quad (5.6)$$

on $x \leq vt$, and $y = 0$ otherwise. To prove this define \tilde{w} to be the solution to

$$\partial_t \tilde{w} = \partial_x^2 \tilde{w} + 2 - (\bar{v} - \bar{\varrho}) - (\bar{f}(\bar{v}) - \bar{f}(\bar{\varrho})) - \tilde{w}.$$

on $x \leq vt$, and $\tilde{w} = 0$ otherwise. Note that by (5.4), $2 - (\bar{v} - \bar{\varrho}) - (\bar{f}(\bar{v}) - \bar{f}(\bar{\varrho})) \geq 0$ and hence $\tilde{w} \geq 0$. Now define

$$y = \bar{v} - \bar{\varrho} + \tilde{w},$$

and by trivial calculations we get that y satisfies (5.6) and since $\tilde{w} \geq 0$, (5.5) follows.

Using the integrating factor e^t we obtain

$$\bar{v}(t, x) - \bar{\varrho}(t, x) \leq \epsilon Z(t, x) + 2 \quad (5.7)$$

where, with $G_v(s, y, t, x)$ as in (2.32),

$$Z(t, x) = \int_0^t \int_0^x e^{-(t-s)} G_v(s, y, t, x) \sigma(s, y) W_1(ds dy) \quad (5.8)$$

So it suffices to show that

$$P(\exists(t, x) \in [0, T] \times \mathbf{R}, x \leq vt : Z(t, x) \geq \epsilon^{-1} e^{-\lambda(x-vt)}) \leq 1/16. \quad (5.9)$$

Note that when we do this we can assume without loss of generality that

$$\sigma^2(t, x) \leq \bar{\varrho}(t, x) + 3e^{-\lambda(x-vt)}. \quad (5.10)$$

For if \tilde{v} is a solution of (3.2) with $\sigma^2(\tilde{v}(t, x))$ replaced by

$$\tilde{\sigma}^2(\tilde{v}, t, x) = \min\left(\sigma^2(\tilde{v}(t, x)), \bar{\varrho}(t, x) + 3e^{-\lambda(x-vt)}\right)$$

then $\bar{v} = \tilde{v}$ up to time

$$\hat{\tau} = \inf\{t \geq 0 : \bar{v}(t, x) \geq \bar{\varrho}(t, x) + 3e^{-\lambda(x-vt)} \text{ for some } x \in \mathbf{R}\}$$

and hence it suffices to prove (5.9) under (5.10). The result now follows from Lemma 4.4. \square

6 Proof of Lemma 2.3

i. of Lemma 6.1 is actually an upgrade of Lemma 2.2 which is a bit stronger than Lemma 2.3. *ii.* is similar to *i.* It is needed in Section 8 to control the maximum of w . Recall \bar{F} from (2.24) and define

$$\underline{F}(x) = \begin{cases} 0, & x \geq 0, \\ u^*/40, & x \in (-M, 0], \\ \bar{F}(x) + 3\lambda e^{-\lambda x}, & x \leq -M, \end{cases} \quad (6.1)$$

Lemma 6.1. *i.* Let v be the solution of (2.31) with initial data (2.24). Let ϱ be the solution of (2.21) with the same initial data. Let γ, L, T, M be as in (2.45)-(2.50). Then

$$P(\exists t \in [0, T] : v(t, x) > \underline{F}(x - vt) \text{ for some } x \in \mathbf{R}) \leq 1/8. \quad (6.2)$$

ii. Suppose that u satisfies $0 \leq u(0, x) \leq \underline{F}(x)$ from (6.1) and

$$\partial_t u \leq \partial_x^2 u + u + \epsilon \sigma(t, x) \dot{W} \quad (6.3)$$

with

$$\sigma(t, x)^2 \leq 3\bar{F}(x - vt - L). \quad (6.4)$$

Suppose M, γ are as in (2.45), (2.47). Then there is a $C_{(6.5)} < \infty$ such that

$$P\left(\sup_{0 \leq t \leq 3, -1 \leq x - vt \leq 1} u(t, x) > u^*/10\right) \leq C_{(6.5)} \gamma \quad (6.5)$$

Let us make a few remarks before we start the proof of the lemma. Note that part (i) of the lemma is only stronger than Lemma 2.2 in the region $x - vt \in (-M, 0]$ where $\bar{\varrho}(t, x) + 3\lambda e^{-\lambda(x-vt)} \sim 3$. We need this to be able to control $\sigma^2(v)$ from below in the regions where v is small, that is in the region $x - vt \in (-M, 0]$. If we will show that with high probability v is small in that region, then we will be able to use (1.5) to control $\sigma^2(v)$ from below there. Another remark deals with coefficient 3 in (6.4). This coefficient appears in (8.15) after which we use Lemma 6.1.

Proof. *i.* Note also that by the same argument as that at (5.10) we can assume that

$$\sigma^2(v(t, x)) \leq \underline{F}(x - vt). \quad (6.6)$$

Let \mathcal{N} be the vertices of an affine lattice in

$$\Gamma = \{(t, x) : 0 \leq t \leq T, vt - M \leq x \leq vt\}$$

with edge length $a\epsilon$ between nearest neighbour vertices. From (2.41) we have that for $(x, t) \in \Gamma$ and therefore for $p \in \mathcal{N}$,

$$E[v(p)] \leq \varrho \leq \epsilon^2 M e^M. \quad (6.7)$$

By Markov's inequality,

$$P(v(p) > u^*/40) \leq 40Me^M \varepsilon^2 / u^*. \quad (6.8)$$

We can estimate

$$P\left(\sup_{p \in \mathcal{N}} v(p) > u^*/40\right) \leq \sum_{p \in \mathcal{N}} P(v(p) > u^*/40) \quad (6.9)$$

and since $|\Gamma| \leq 2MT\varepsilon^{-2}a^{-2}$, if $a \geq 80M^{1/2}e^{M/2}(u^*)^{-1/2}$ then

$$P\left(\sup_{p \in \mathcal{N}} v(p) > u^*/40\right) \leq 1/32. \quad (6.10)$$

Hence to prove the lemma it suffices to show that if $a \leq C_{(6.18)}^{-1} \varepsilon^{-1} u^*$ then

$$P\left(\sup_{\substack{(t,x), (t',x') \in \Gamma \\ |x'-x|+|t'-t| \leq a\varepsilon}} |v(t',x') - v(t,x)| \geq u^*/40\right) \leq 1/16. \quad (6.11)$$

Divide Γ into T intervals of length 1, $\Gamma^i = \Gamma \cap \{i \leq t \leq i+1\}$. On $\{i \leq t \leq i+1\}$, v is the solution to

$$v(t, x) = \int G_v(i, y, t, x) v(i, y) dy + \int \int_i^t G_v(s, y, t, x) f(v(s, y)) ds dy + \varepsilon Z(t, x). \quad (6.12)$$

where

$$Z(t, x) = \int \int_i^t G_v(s, y, t, x) \sigma(v, s, y) W_1(ds dy). \quad (6.13)$$

From (6.6), assuming $t' \geq t$,

$$|v(t', x') - v(t, x)| \leq \Omega_1 + \Omega_2 + \Omega_3 + \varepsilon |Z(t', x')| + \varepsilon |Z(t, x)|. \quad (6.14)$$

where

$$\Omega_1 = 3 \int |G_v(i, y, t', x') - G_v(i, y, t, x)| e^{-\lambda(y-vi)} dy, \quad (6.15)$$

$$\Omega_2 = 3 \int \int_i^{t_1} |G_v(s, y, t', x') - G_v(s, y, t, x)| e^{-\lambda(y-vs)} ds dy, \quad (6.16)$$

$$\Omega_3 = 3 \int \int_t^{t'} G_v(s, y, t', x') e^{-\lambda(y-vs)} ds dy. \quad (6.17)$$

So the result follows from (4.44) and the elementary fact that there exists $c < \infty$ such that if $|t - t'| + |x - x'| \leq cu^*$, $\lambda, v \in [1, 2]$ then

$$\Omega_1 + \Omega_2 + \Omega_3 \leq u^*/80. \quad (6.18)$$

ii. From (6.3),

$$u(t, x) \leq e^t \int G(0, y, t, x) \underline{F}(y) dy + \epsilon e^t Z(t, x) \quad (6.19)$$

where

$$Z(t, x) = \int \int_0^t e^{-s} G(s, y, t, x) \sigma(s, y) W(ds dy) \quad (6.20)$$

From the definition of \underline{F} it is clear that we can choose M so that for all $0 \leq t \leq 3$ and $-1 \leq x - vt \leq 1$,

$$\int e^t G(0, y, t, x) \underline{F}(y) dy < u^*/20. \quad (6.21)$$

so the result follows from the following large deviation estimate whose proof is elementary as it only has to hold on time intervals of order 1: There exists a $C_{(6.5)} < \infty$ such that for γ is as in (2.47),

$$P\left(\sup_{0 \leq t \leq 3, -1 \leq x - vt \leq 1} \epsilon e^t |Z(t, x)| > u^*/20\right) \leq C_{(6.5)} \gamma. \quad (6.22)$$

□

7 The critical mass

The following elementary computation identifies the critical mass for survival.

Lemma 7.1. *Let \dot{W} be a white noise and $w(t, x)$ be a positive solution of*

$$\partial_t w = \partial_x^2 w + bw + \vartheta \sqrt{w} \dot{W}, \quad w(0, x) = w_0 \quad (7.1)$$

where ϑ is adapted with $\vartheta \geq \vartheta_0$ for some nonrandom $\vartheta_0 > 0$. Then

$$P(w(t) \equiv 0) \geq 1 - e^{bt} \vartheta_0^{-2} t^{-1} E\left[\int w_0(x) dx\right] \quad (7.2)$$

Proof. By considering $\tilde{w} = e^{-bt} w$ we can assume without loss of generality that $b = 0$. If

$$\partial_t \phi = \partial_x^2 \phi - \vartheta_0^2 \phi^2 \quad (7.3)$$

then

$$\exp\left\{-\int \phi(t-s, x), w(s, x) dx\right\} \quad (7.4)$$

is a supermartingale in the s variable on $[0, t]$. The solution of (7.3) with $\phi(0, x) = n$ is $\phi(t, x) = (\vartheta_0^2 t + n^{-1})^{-1}$ and hence

$$E[\exp\{-n \int w(t, x) dx\} \mid \mathcal{F}_0] = \exp\{-(\vartheta_0^2 t + n^{-1})^{-1} \int w(0, x) dx\}. \quad (7.5)$$

Taking $n \rightarrow \infty$ we get

$$P(\int w(t, x) dx = 0) = E[\exp\{-\vartheta_0^{-2} t^{-1} \int w(0, x) dx\}] \quad (7.6)$$

and the lemma follows from $e^{-x} \geq 1 - x$. □

The next lemma is needed to control the support of such a w in short time intervals, in terms of the immigration. Note that we will only have to have reasonable control, and the actual scale are not critical here, as it is in the previous lemma.

Lemma 7.2. *Let W be a white noise and w be a solution of*

$$\partial_t w = \partial_x^2 w + bw + \vartheta \sqrt{w} \dot{W} + d\mu, \quad 0 \leq t \leq 1 \quad (7.7)$$

with $w(0, x) \equiv 0$ and let ψ be the hitting time of $(-r, r)^c$;

$$\psi = \inf\{t \geq 0 : \text{supp}(w(t)) \cap (-r, r)^c \neq \emptyset\}. \quad (7.8)$$

Suppose that μ is a positive adapted measure on $[0, 1] \times \mathbf{R}$ with support in $[0, 1] \times (-r/2, r/2)$, and ϑ is adapted and $\vartheta \geq \vartheta_0 > 0$. Then, letting $M = \int \int_0^1 \mu(dt dx)$,

$$P(\psi > 1) \geq 1 - 100r^{-2}e^b\vartheta_0^{-2}E[M]. \quad (7.9)$$

Proof. By considering $\tilde{w} = \vartheta_0^2 e^{-bt} w$ we can assume without loss of generality that $b = 0$ and $\vartheta_0 = 1$. Furthermore, by symmetry it is enough to prove the result when ψ is the hitting time of $(-\infty, -r]$ with a constant 50 instead of 100 on the right hand side. First let us consider the case $\mu(t) \in \mathcal{F}_0$. Note that for any $\delta > 0$

$$g_\delta(x) = 12(x + r + \delta)^{-2} \quad (7.10)$$

satisfies $\partial_x^2 g_\delta = g_\delta^2/2$ for $x > -r - \delta/2$. Let

$$X_\delta(t) = \exp \left\{ - \int g_\delta(x) w(t, x) dx + \int \int_0^t g_\delta(x) \mu(ds dx) \right\}. \quad (7.11)$$

Then $X_\delta(t \wedge \psi)$ is a submartingale. In particular,

$$E[X_\delta(1 \wedge \psi) \mid \mathcal{F}_0] \geq E[X_\delta(0) \mid \mathcal{F}_0] = 1. \quad (7.12)$$

Let us assume temporarily that $\mu(t) \in \mathcal{F}_0$, $0 \leq t \leq 1$. Since $g \geq 0$, and $g \leq 48r^{-2}$ on $\text{supp}(\mu)$ we have $M_{g_\delta}(1 \wedge \psi) \leq M_{g_\delta}(1) \leq 48r^{-2}M$,

$$E \left[\exp \left\{ - \int g_\delta(x) w(1 \wedge \psi, x) dx \right\} \mid \mathcal{F}_0 \right] \geq \exp \{-48r^{-2}M\}. \quad (7.13)$$

Note that

$$P(\psi > 1) \geq \liminf_{\delta \rightarrow 0} E \left[\exp \left\{ - \int g_\delta(x) w(1 \wedge \psi, x) dx \right\} \mid \mathcal{F}_0 \right] \quad (7.14)$$

which proves the lemma when $\mu(t) \in \mathcal{F}_0$.

For the general case, note first that (7.7) has the property that if w_1 and w_2 are two solutions with measures μ_1 and μ_2 and independent white noises W_1 and W_2 , then $w_1 + w_2$ is a solution with measure $\mu_1 + \mu_2$.

We construct a probability space on which we have this setup with adapted ϑ and $\mu_i(dx, dt) = \mu_i(dx)\delta_{t_i}(dt)$. Let ψ_1 and ψ_2 be the corresponding hitting times of $(-\infty, -r]$. From (7.13) and (7.14), conditioning on \mathcal{F}_{t_i} instead of \mathcal{F}_0 we have $P(\psi_i > T) \geq \exp\{-48r^{-2}M_i\}$ for $i = 1, 2$ with $M_i = \int \mu_i(dx)$ and hence $P(\psi_1 \wedge \psi_2 > 1) \geq E[\exp\{-48r^{-2}(M_1 + M_2)\}]$.

A finite induction then gives the result for $\mu(dt dx) = \sum_{n=0}^N \mu_n(dx)\delta_{t_n}(dt)$ with $\mu_n(dx) \in \mathcal{F}_{t_n}$. We can then take limits to obtain the result for all adapted positive measures μ . \square

8 Proof of Lemma 2.4

We will solve (3.6) iteratively, on short time intervals of length 1 and show that we can kill the mass of w on each interval separately. The reason to do this is that the noise in (3.6), which is needed to kill the mass, is only of the correct order near $x = vt$ where v is relatively small. So one has to show that the mass vanishes quickly, before the front moves ahead, and the noise is no longer available. We will do all our bounds on the event $\{v(t, x) \leq \underline{F}(t - vt)\}$ where \underline{F} is defined in (6.1). To be more precise, define

$$\tau_v = \inf\{t \geq 0 : v(t, x) \geq \underline{F}(x - vt) \text{ for some } x \in \mathbf{R}\}. \quad (8.1)$$

Let

$$\tilde{v}(t, \cdot) = v(t \wedge \tau_v, \cdot).$$

Let $W_{2,k}$, $k = 1, 2, \dots$ be a sequence of independent white noises which are also independent of W_1 . We construct a sequence of processes \bar{w}_k , $k = 1, 2, \dots$ by solving

$$\begin{cases} \partial_t \bar{w}_k = \partial_x^2 \bar{w}_k + \|f\|_{\text{Lip}} \bar{w}_k + \epsilon \sigma_k \dot{W}_{2,k} + \delta_{x-vt} \dot{A}_k & k-1 < t \leq k+1, \\ \bar{w}_k(t, \cdot) = 0 & t = k-1, \end{cases} \quad (8.2)$$

and setting $\bar{w}_k(t, \cdot) = 0$ for $t \in (k-1, k+1]^c$. Here

$$\sigma_k^2 = |\sigma^2(\tilde{v} + \bar{w}_k + \bar{w}_{k-1}) - \sigma^2(\tilde{v} + \bar{w}_{k-1})| \vee a^* \bar{w}_k \quad (8.3)$$

and

$$\dot{A}_k = \dot{A} 1_{k-1 < t \leq k} \quad (8.4)$$

is the creation term acting only on the first half of each time interval. To start things going we use the convention that $\bar{w}_{-1} = \bar{w}_0 \equiv 0$. Define stopping times

$$\begin{aligned} \tau_{k,1} &= \inf\{t \in (k-1, k+1] : \text{supp}\{\bar{w}_k(t)\} \not\subset (v(k-1) - 1, vk + 1)\}, \\ \tau_{k,2} &= \inf\{t \in (k-2, k+1] : \bar{w}_k(t, x) + \bar{w}_{k-1}(t, x) + \tilde{v}(t, x) > u^*/10 \\ &\quad \text{for some } x \in (v(k-2) - 1, vk + 1)\}, \\ \tau_{k,3} &= \begin{cases} \infty, & \text{if } \bar{w}_k(k+1, \cdot) \equiv 0, \\ k+1, & \text{otherwise.} \end{cases} \end{aligned}$$

with the convention that the infimum is infinite if the set is empty, and $\text{supp}\{w\} = \{x : w(x) > 0\}$ is the support of a non-negative function w .

Let $\tau = \tau_{k,i}$ be the smallest $\tau_{k,i} < T$, if there is one. Otherwise let $\tau = T$. Note that up to time $\tau \wedge (k+1)$ we have

$$\sigma_k^2 = \sigma^2(\tilde{v} + \bar{w}_k + \bar{w}_{k-1}) - \sigma^2(\tilde{v} + \bar{w}_{k-1}).$$

Hence, we can find a probability space on which there are white noises W_2 and $\{W_{2,i}, i = 1, 2\}$ such that the solution \bar{w} of (2.38) can be represented as

$$\bar{w}(t, x) 1(t \leq \tau \wedge \tau_v) = \sum_{k=1}^{\infty} \bar{w}_k(t, x) 1(k-1 < t \leq (k+1) \wedge \tau \wedge \tau_v). \quad (8.5)$$

For each $k = 1, \dots, T$ let

$$U_k = \{\tau_{k,1} > k+1\} \cap \{\tau_{k,2} > k+1\} \cap \{\tau_{k,3} > k+1\} \quad (8.6)$$

Recall γ from (2.47). We claim that

$$P(\cap_{k=1}^T U_k) \geq 1 - c_0 \gamma T. \quad (8.7)$$

This implies Lemma 2.4, for on $\cap_{k=1}^T U_k \cap \{\tau_v > T\}$,

$$\bar{w}(t, x) = \sum_{k=1}^{\infty} \bar{w}_k(t, x) 1(k-1 < t \leq k+1), \quad t \leq T. \quad (8.8)$$

Hence the left hand side of (2.53) is bounded above by

$$1 - P(\cap_{k=1}^T U_k \cap \{\tau_v > T\}) \leq c_0 \gamma T + 1/8,$$

since $P(\tau_v < T) < 1/8$ by Lemma 6.1, and we are done.

The rest of the section will be devoted to verifying (8.7). Clearly it suffices to prove that for each $k = 1, \dots, T$ and $i = 1, 2, 3$,

$$P(\tau_{k,i} \leq k+1) \leq c_0 \gamma. \quad (8.9)$$

By Lemma 7.1, applied to \bar{w}_k on the interval $[k, k+1]$ where there is no creation acting on \bar{w}_k ,

$$P(\tau_{k,3} \leq k+1) \leq C_{(8.10)} \epsilon^{-2} E[A(k) - A(k-1)] \leq 2C_{(8.10)} \gamma, \quad (8.10)$$

where $C_{(8.10)} = e^{\|f\|_{\text{Lip}}(a^*)^{-1}}$. In the last inequality we used (2.44). By the same reasoning, but using Lemma 7.2 instead of Lemma 7.1, there is a $C_{(8.11)} < \infty$ such that

$$P(\tau_{k,1} \leq k+1) \leq C_{(8.11)} \gamma. \quad (8.11)$$

It remains to prove (8.9) for $\tau_{k,2}$. The rest of the proof is devoted to this. Define

$$u_k(t) = \bar{w}_k(t, x) + \bar{w}_{k-1}(t, x) + \tilde{v}(t, x), \quad t \in [k-2, k+1]. \quad (8.12)$$

Given that $\bar{w}_k(k-1, \cdot) = \bar{w}_{k-2}(k-1, \cdot) = 0$ there is a white noise $\dot{W}_{(k)}$ such that

$$\partial_t u_k = \partial_x^2 u_k + (\bar{w}_k + \bar{w}_{k-1}) + f(\tilde{v}) + \epsilon \sigma_{(k)} \dot{W}_{(k)}, \quad (8.13)$$

where $\sigma_{(k)}^2 = \sigma_{k-1}^2 + \sigma_k^2 + \sigma(\tilde{v})^2$. Since $f(\tilde{v}) \leq \tilde{v}$,

$$\partial_t u_k \leq \partial_x^2 u_k + u_k + \epsilon \sigma_{(k)} \dot{W}_{(k)}. \quad (8.14)$$

The inequality is meant as holding for the corresponding integral equation. Now we claim that on $\{\tau_{k,1} > k+1\} \cap \{\tau_{k-1,1} > k\}$, we have, for $t \leq \tau_{k,2}$

$$\sigma_{(k)}^2(t, x) \leq (\|\sigma^2\|_{\text{Lip}} + 2) \bar{F}(x - vt - L). \quad (8.15)$$

For we know that there $\sigma^2(\tilde{v}(t, x)) \leq \tilde{v}(t, x) \leq \underline{F}(x - vt) \leq \bar{F}(x - vt - L)$. Also $\sigma_k^2(t, x) \leq \|\sigma^2\|_{\text{Lip}} \bar{w}_k(t, x) \leq \|\sigma^2\|_{\text{Lip}} \frac{u^*}{10} 1_{\{(k-1, k+1] \times (v(k-1)-1, vk+1)\}} \leq \|\sigma^2\|_{\text{Lip}} \bar{F}(x - vt - L)$.

Note that

$$P(\tau_{k,2} \leq k+1, \tau_{k,1} > k+1, \tau_{k-1,1} > k) \leq P\left(\sup_{\substack{k-2 \leq t \leq k+1 \\ v(k-2)-1 \leq x \leq vk+1}} u_k(t, x) > u^*/10\right). \quad (8.16)$$

We want to estimate this with Lemma 6.1, but we need (6.4), which does not necessarily hold. But by the argument around (5.10), in proving (6.4), we can assume without loss of generality that (8.15) holds. In fact this is the place where it is clear the appearance of coefficient 3 in (6.4). Hence we can apply Lemma 6.1 to obtain

$$P(\tau_{k,2} \leq k+1, \tau_{k,1} > k+1, \tau_{k-1,1} > k) \leq C_{(6.5)} \gamma. \quad (8.17)$$

Finally,

$$\begin{aligned} P(\tau_{k,2} \leq k+1) &\leq P(\tau_{k,2} \leq k+1, \tau_{k,1} > k+1, \tau_{k-1,1} > k) + P(\tau_{k-1,1} \leq k) \\ &\quad + P(\tau_{k,1} \leq k+1) \\ &\leq (C_{(6.5)} + 2C_{(8.11)})\gamma, \end{aligned}$$

which completes the proof of Lemma 2.4.

9 Proof of Lemma 2.6

We need a preliminary result of how a stochastic perturbation of a partial differential equation stays close to its deterministic version. Here the interval is of order 1, but the estimate needs to be precise.

Lemma 9.1. *Suppose that u and ϱ are solutions of*

$$\partial_t u = \partial_x^2 u + f(u) + \sigma(u) \dot{W} \quad (9.1)$$

and

$$\partial_t \varrho = \partial_x^2 \varrho + f(\varrho) \quad (9.2)$$

on $|x| < L + vt$, $0 < t \leq T$ with $u(t, x) = \varrho(t, x) = 0$ on $|x| \geq L + vt$, and $u(0, x) = \varrho(0, x)$. Suppose that f is Lipschitz with constant K . Then

$$|u(t, x) - \varrho(t, x)| \leq |\tilde{Z}(t, x)| + |Z(t, x)|. \quad (9.3)$$

where

$$\tilde{Z}(t, x) = K \int_0^t \int_0^s e^{K(t-s)} G_{v,L}(s, y, t, x) |Z(s, y)| ds dy, \quad (9.4)$$

$$Z(t, x) = \int_0^t \int_0^s G_{v,L}(s, y, t, x) \sigma(u(s, y)) W(ds dy). \quad (9.5)$$

Proof. Let $D = u - \varrho - Z$. Note that D satisfies

$$\partial_t D = \partial_x^2 D + f(D + \varrho + Z) - f(\varrho) \quad (9.6)$$

on $|x| < L + vt$ with $D(t, x) = 0$ on $|x| \geq L + vt$ and $t = 0$. Now $|f(D + \varrho + v) - f(\varrho)| \leq K|D| + K|v|$. Let D_+ and D_- be the solutions of

$$\partial_t D_{\pm} = \partial_x^2 D_{\pm} \pm K[|D_{\pm}| + |Z|], \quad |x| < L + vt \quad (9.7)$$

with $D_{\pm}(t, x) = 0$ for $|x| \geq L + vt$ and $D_{\pm}(0, x) = 0$. Note that D_+ is a supersolution and D_- is a subsolution of (9.6), so that $D_- \leq D \leq D_+$. Furthermore, $D_- \leq 0 \leq D_+$, so (9.7) can be solved explicitly in terms of Z . We get

$$D_{\pm}(t, x) = \pm K \int_0^t \int_0^s e^{K(t-s)} G_{v,L}(s, y, t, x) |Z(s, y)| ds dy. \quad (9.8)$$

as desired. \square

Now we continue with the proof of Lemma 2.6. Define

$$\hat{\varrho}(t, x) = \underline{\varrho}(t, x) + r\epsilon \sqrt{\mathcal{G}\underline{\varrho}(t, x)} \quad (9.9)$$

$$h(x) = (1 + |x|) \exp\left\{\left(1 - \frac{\delta}{2}\right)|x|\right\} \quad (9.10)$$

Proof of Lemma 2.6. Let

$$\mathcal{A} = \left\{ \omega : |\underline{u}(t, x) - \underline{\varrho}(t, x)| \leq \epsilon r \sqrt{\mathcal{G}\underline{\varrho}(t, x)}, \ 0 \leq t \leq 1, x \in \mathbf{R} \right\}. \quad (9.11)$$

In particular, on \mathcal{A} , we have

$$\underline{u}(t, x) \leq \hat{\varrho}(t, x), \quad 0 \leq t \leq 1, x \in \mathbf{R}. \quad (9.12)$$

If we were to let $\tilde{\sigma}(t, x) = \sqrt{\min\{\sigma^2(t, x), \hat{\varrho}(t, x)\}}$, and \tilde{u} be the solution of (2.66) with σ replaced by $\tilde{\sigma}$, and $\tilde{\mathcal{A}}$ the analogue of \mathcal{A} with u replaced by \tilde{u} , then $P(\mathcal{A}) = P(\tilde{\mathcal{A}})$. Hence in estimating $P(\mathcal{A})$ we can assume without loss of generality that

$$\sigma^2(t, x) \leq \hat{\varrho}(t, x). \quad (9.13)$$

\underline{f} is Lipschitz with constant 1, so by Lemma 9.1,

$$|\underline{u}(t, x) - \underline{\varrho}(t, x)| \leq \epsilon |\tilde{Z}(t, x)| + \epsilon |Z(t, x)|, \quad (9.14)$$

where $\tilde{Z}(t, x)$ and $Z(t, x)$ are as in (9.4) and (9.5) with u replaced by \underline{u} and $K = 1$.

Now note that there exists $C_{(9.15)} < \infty$ such that for $0 \leq t \leq 1$,

$$\hat{\varrho}(t, x) \leq C_{(9.15)} \epsilon^2 \gamma h(x - vt + L). \quad (9.15)$$

By Lemmas 4.1 and 4.2 with $T = 1$, and $a = 1$, and by (9.15), we have, for some $C_{(9.16)} < \infty$,

$$P\left(\sup_{\substack{0 \leq t \leq 1 \\ x - vt \in [b-1, b]}} |Z(t, x)| \geq r\epsilon\gamma^{1/2}\sqrt{h(b)}\right) \leq 4\exp\{-C_{(9.16)}^{-1}r^2\}. \quad (9.16)$$

Furthermore there exists $C_{(9.17)} < \infty$ such that for $0 \leq t \leq 1$,

$$\epsilon^2\gamma h(x - vt + L) \leq C_{(9.17)}\mathcal{G}_{\underline{\rho}}(t, x) \quad x \leq vt + L \quad (9.17)$$

so summing b from 0 to L and using (9.17),

$$P(\epsilon|Z(1, x)| \leq r\epsilon\sqrt{\mathcal{G}_{\underline{\rho}}(1, x)} \text{ for all } x \in [v, v + L]) \geq 1 - 4L\exp\{-C_{(9.18)}^{-1}r^2\}. \quad (9.18)$$

Finally, it is not hard to check that there is a $C_{(9.19)} < \infty$ such that for $0 \leq t \leq 1$,

$$\int_0^t \int_0^s e^{t-s} G_{v,L}(s, y, t, x) \sqrt{h(y + L)} ds dy \leq C_{(9.19)} \sqrt{h(x - vt + L)}, \quad (9.19)$$

and therefore we also have for some $C_{(9.20)} < \infty$,

$$P(\epsilon|\tilde{Z}(1, x)| \leq r\epsilon\sqrt{\mathcal{G}_{\underline{\rho}}(t, x)} \text{ for all } x \in [v, v + L]) \geq 1 - 4L\exp\{-C_{(9.20)}^{-1}r^2\}, \quad (9.20)$$

which completes the proof of Lemma 2.6. \square

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